## User manual

# CPS\_CPS 10 System



Part Number: NPCPSGB Revision: J.2



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June 2018

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- \* This equipment will only provide the announced performance levels if it is used, maintained and repaired according to OLDHAM directives, by OLDHAM personnel or by personnel approved by OLDHAM
- \* The CPS model is not intended to be used as Life Safety Equipment

### GUARANTEE

2 years guarantee in normal conditions of use on parts and technical labour, return in our workshops, excluding consumables (sensors, filters, etc.)

### **General Information**

Please read the following notice carefully before installation and start-up, paying particular attention to the end-user material safety instructions. This user's guide should be distributed to every individual involved in the installation, operation, maintenance or repair of the CPS system.

The information contained in this manual, the data and technical drawings are correct as of the date of publication. Should guestions arise, please contact OLDHAM for additional information.

This manual is designed to provide users with simple and precise information. OLDHAM shall is not responsible or liable for any misinterpretation that may result from the reading of this manual. Although every effort is made to ensure accuracy, this manual may contain unintentional technical inaccuracies.

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This manual is a translation of the French original. In case of discrepancy between the French version and any translated version, the French version shall take precedence and shall prevail in all matters pertaining to any relationship between the parties.

This icon indicates that there is additional useful information for a particular topic.

### Safety Warnings

Pictogram labels have been placed on the central controller to call attention to general use safety precautions. These labels are an integral component of the central controller. Replace any label that has peeled off or become illegible. The meanings of these labels are explained below.



Ground terminal



Safety ground terminal



Risk of electric shock



Caution (see accompanying documentation)





### **WARNING**

The installation of this product and all electrical connections should be performed by a qualified professional, in accordance with the manufacturer's specifications and with the standards of authorities in the field.

Failure to observe these warnings may result in serious injury. Exercise great caution, particularly when working with electricity during installation (couplings, network connections).



European Union (and EEA) only. This icon indicates that in accordance with Directive DEEE (2002/96/CE) and with the regulations specific to your country, this product may not be disposed of with household waste.

Dispose of this product at a collection site intended for electrical waste, for example an official EEE (electrical and electronic equipment) collection site with a recycling or take-back program for authorized products which are available to consumers whose purchases are intended to replace old EEE products with new equivalents.

Failure to comply with regulations for the disposal of this type of waste can be harmful to the environment and to public health, as EEE products typically contain substances that may be dangerous. Your complete cooperation with the disposal of this product will help to ensure a more efficient use of natural resources.

### Important Information

The modification of any piece of equipment or the use of any third party parts will automatically void all quarantees.

The central controller is intended to be used for precise applications of a technical nature. Exceeding the indicated values is strictly prohibited.

The use of the unit has been projected for the applications specified in the technical characteristics. Exceeding the indicated values cannot in any case be authorized.

Catalytic sensors are susceptible to poisoning by traces of several substances. This leads to an inhibition which can be permanent or temporary depending on the contaminant, the concentration of the contaminant, the duration of exposure to the contaminant.

Poisoning may result from exposure to substances as:

- silicones (e.g. waterproofing, adhesives, release agents, special oils and greases, certain medical products, commercial cleaning agents)
- tetraethyl lead (e.g. leaded petrol, particularly aviation petrol 'Avgas')
- sulfur compounds (sulfur dioxide, hydrogen sulfide)
- halogenated compounds (R134a, HFO, etc.)
- organo-phosphorus compounds (e.g. herbicides, insecticides, and phosphate esters in fireproof hydraulic fluids

Oldham recommends regular testing of fixed gas detection installations (read Chapter 6).

# **Table of Contents**

Chapter 1	Overview of the CPS System	8
	controller	
	e modules	
	oftware application	
System Architectu	re	13
Chapter 2	Assembly / Installation	14
Installation of the	e CPS central controller	14
	al wall casing4U rack	
	modules	
	3 10 sensor module	
Mounting the othe	r modules	15
Connection of mod	dules in a line	15
Chapter 3	The CPS Central Measuring Contro	ller16
-	nted CPS	
	ted CPS	
	r electrical connections	
	y	
	ntral controller	
Internal relay dry of	contacts	17
	outlotherboard	
	ital buses	
	L	
	buzzerial connectors	
RS-485 serial con	nection (3)	21
	eature)	
-	ircuit	
Keys		23
-		
	S	
Alarm acknowled	lgement	24
Chapter 4	Digital Modules	26
	odules	
	al Modules	
	of the RS-485 network	
Configuring the o	communication settings	28
	Г	
	Module	
	Types	
Detector settings		29
_	odule	
	relay security	
	n	
Logic Input Modu	ıle	33

Analog Outputs Module		33
Chapter 5	Detailed Menus	36
Menu Tree		36
•		
Sensor Display		38
	tus	
-		
-	Action	
Start-up Configuration	on	42
Maintenance Menu		43
Simulation		43
Treset maintenance		40
Chapter 6	Maintenance	47
Program transfer		47
PC → CPS transfer.		47
Error messages		48
Testing and calibra	ation of stable installations	49
	bration	
	bration device	
	maintenance	
	namenance	
	k	
	System	
Chapter 7	Technical Specifications	
	oller	
CPS 10 Sensor Mo	dule	56
CPS RM4 or RM8 F	Relay Module	56
CPS DI16 Logic Inp	outs Module	56
CPS AO4 Analog C	Output Module	56
Chapter 8	Annexes	57
Chapter 9	UE Declaration of Conformity	73

# **Chapter 1** Overview of the CPS System

The system consists of:

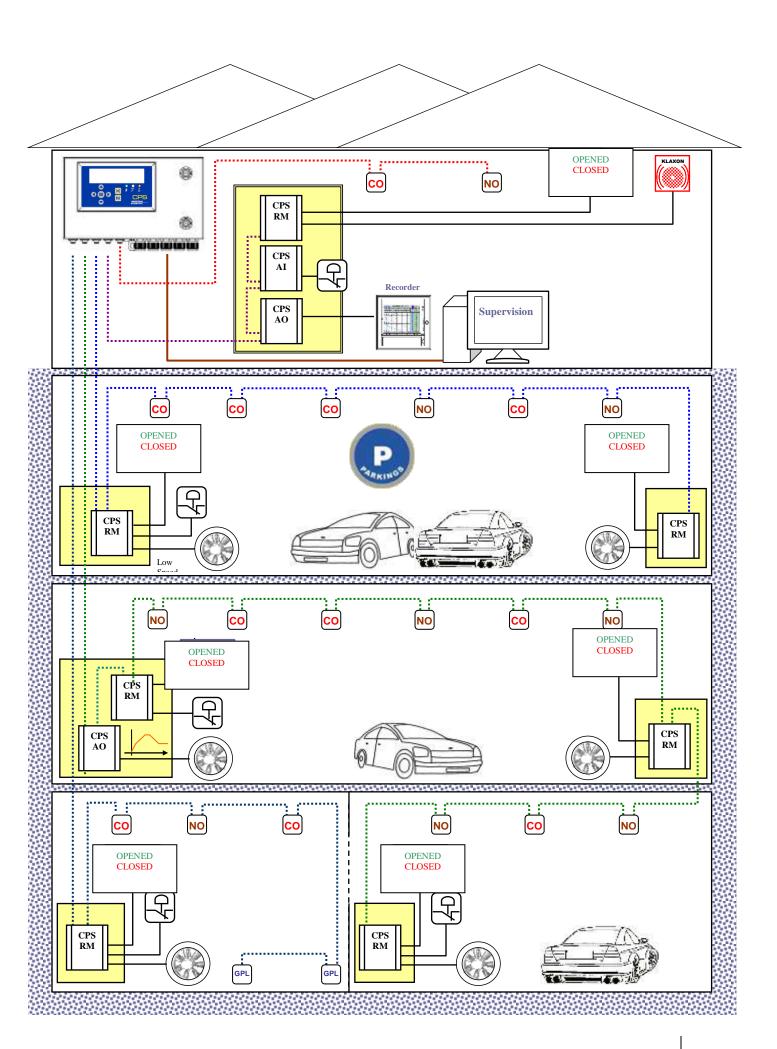
- a central controller for collecting readings and managing alarms;
- various addressable digital modules (sensor modules, relay modules, analog output modules, logic input modules);
- instruments and accessories to process alarms and actions

The CPS system can manage the detection of **10 different gases**, and all detectors are clearly localized and identified.

Data from each sensor is collected in the central controller in less than one second. If gas levels exceed the programmed limits, an audiovisual alarm is triggered and can activate the ventilation system in the affected area of the parking facility.

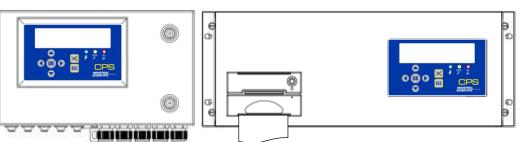
Use the **COM\_CPS software** to program the central controller.

The system status can be quickly verified with semi-automatic calibration for various sensors.



### The CPS central controller

CPS: Wall mounted version



CPS: Rack mounted 19" 4U

The central controller is available in a 19" 4U (rack-mount) version or in a wall-mount version. It is designed to control:

- 256 digital modules distributed over 8 lines, with a maximum of 32 modules per line;
- 256 addressable relays max. distributed across all relay modules;
- 224 logic inputs max. distributed across all logic input modules and relay modules.
- 256 analog outputs max. distributed across 4 analog outputs modules.

Modules are connected through a digital RS-485 network using JBUS/MODBUS protocol.

The central controller connects to 256 toxic sensors, and runs on only 24 Watts.

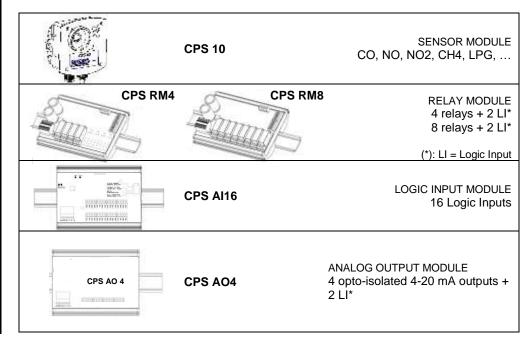
The central controller can be connected to a supervision system via an RS-485 output interface using ModBus protocol.

### Optional features include:

- a battery back-up, ensuring continual operation in case of a power outage (approx. 1 hour for 50 TOX-type sensors);
- an integrated printer (rack-mounted version only) for recording alarms and events;
- an external printer (for both rack- and wall-mounted versions).

### **Digital addressable modules**

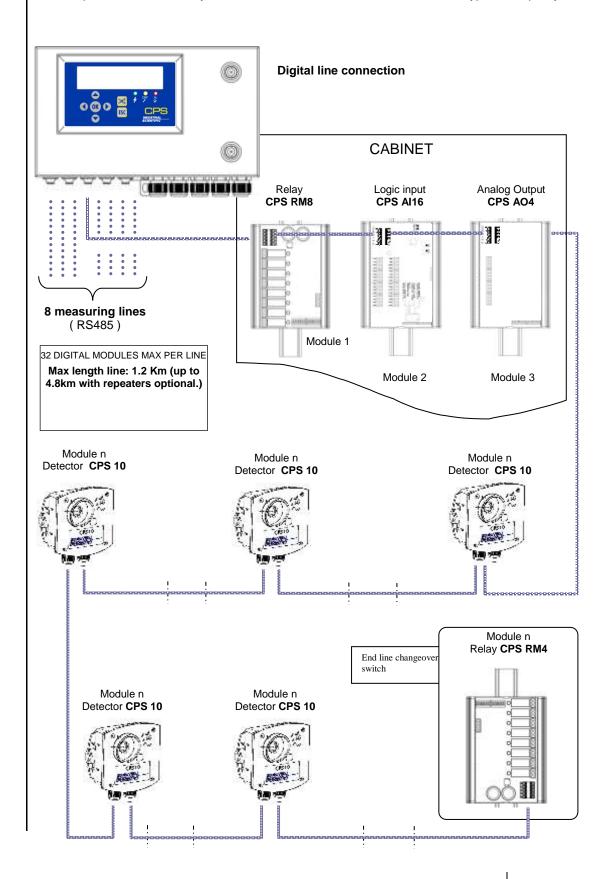
Various digital addressable modules can be positioned on the same line.



### **Digital linking**

Modules are linked in-line via an MPI 22 or equivalent RS-485 double twisted pair cable, at least 0.22 mm² in diameter. One pair supplies power to the module, the second pair is used for the digital RS-485 link

ISC - personnel should verify that the correct cable has been used in terms of type and capacity.



### The COM\_CPS software application

The **COM\_CPS** software application is designed to help configure the CPS central measuring controller on a PC. COM\_CPS software operations are addressed in a separate manual.

### **System and Hardware Requirements:**

COM\_CPS must be installed on a PC running Windows 2000 or Windows XP.

The minimum requirements to install COM\_CPS are:

- Windows 98 SE, Windows NT, Windows 2000, Windows XP with 256 MB RAM, Windows VISTA.
- A CD-ROM drive
- At least 10 MB of free hard drive space
- A USB connection (cable not included) or a free RS-232 port (specific cable provided) to link the CPS central measuring controller to the PC.

Refer to the COM\_CPS software instructions before installing or using the software, and before programming the central controller.

The COM\_CPS software allows you to:

- configure one or more central controller(s) via PC;
- save settings and upload them later to the CPS central controller(s).
- view or modify central controller configuration data within the application.

The COM\_CPS software can be used to modify the following main configuration settings:

- STEL and TWA calculations
- Predefined status tables printing times
- Conditions that would activate an internal buzzer
- Communication speed for the RS-485 series connection with a master device
- Settings for various sensors and alarm values
- Personalized sensor add-on options
- Delay settings
- Rising edge or falling edge triggers
- Average alarm integration time
- Verification of explosive gasses
- Creation of installation architecture: sensors/relays

COM\_CPS

Whenever this sign appears in front of a chapter, the functions described in that chapter are configured with the COM\_CPS software.

# **System Architecture Rack mounted Control unit CPS** SUPERVISION Integrated printer (option) only for rack Mounted CPS COM\_CPS PC configuration Recorder Serial Printer 8 available digital RS485 Lines 32 addressable modules max per line 256 modules per central CPS Analog output CPS AO4 Detector module CPS 10 Logic input module CPS AI16 Relay module CPS RM4 Relay module CPS RM8

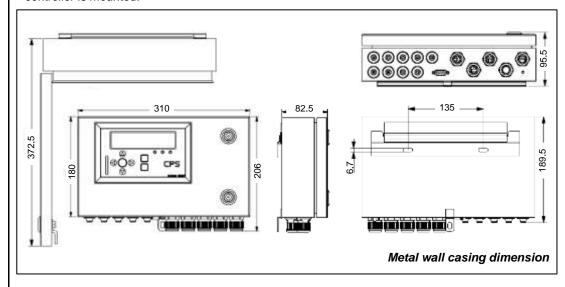
# **Chapter 2** Assembly / Installation

### Installation of the CPS central controller

The CPS central controller should be installed in a dry, climate-controlled area protected from explosive gases and dust. Ideally, the station should be located in a secure, accessible location under surveillance (security office, control room, equipment room ...).

### Mounting the metal wall casing

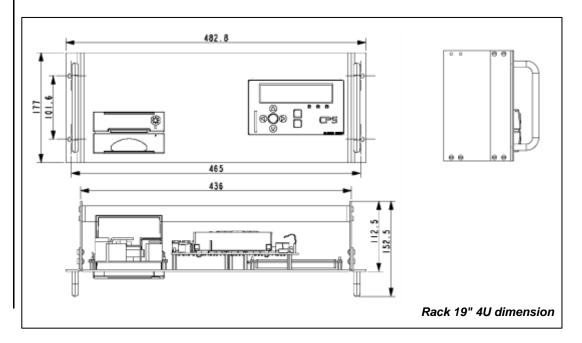
For the wall-mounted CPS in a metal case: The central controller cover opens at a 90° angle to the left. Make sure to leave adequate space to completely open the cover once the central controller is mounted.



### Mounting the 19" 4U rack

### The 19" 4U rack version CPS can be integrated into a rack or a 19" cabinet:

Mount the display at eye level for optimal viewing. Leave at least ½ U (22 mm) on all sides of the central controller to ensure proper ventilation.



### **Installing digital modules**

### Mounting the CPS 10 sensor module

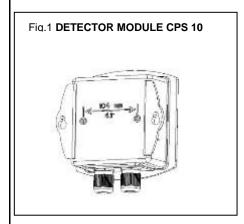
Mount the sensor modules on a flat surface using two screws (Fig. 1).

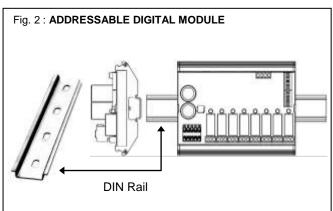
The modules should be placed in an accessible area, so that maintenance and inspection operations can be conducted as easily and as safely as possible. Nothing in the area should prevent the sensors from obtaining measurements of the ambient environment.

When mounting the sensor module on a vertical surface, position the cable glands on the underside of the module to ensure proper calibration.

### Mounting the other modules

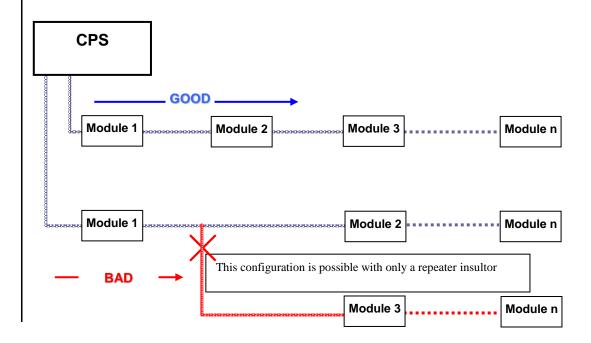
The other modules (relay, logic input, analog output) should be mounted on a DIN rail inside of a cabinet or an electric box. (Fig. 2).





### Connection of modules in a line

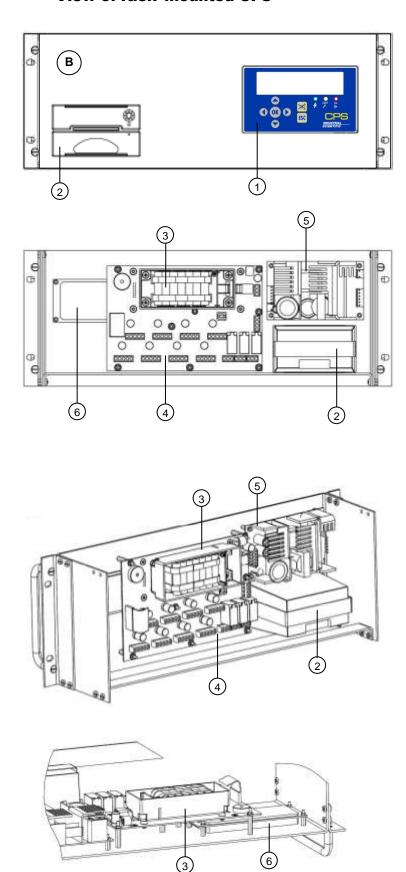
**1 IMPORTANT**: All modules in a line should be wired in-line from the central controller, not in a hub and spoke model.

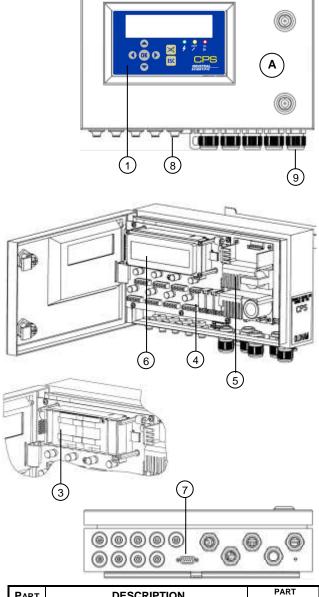


# **Chapter 3** The CPS Central Measuring Controller

**View of rack-mounted CPS** 

**View of wall-mounted CPS** 





PART	DESCRIPTION	PART NUMBER
Α	CPS WALL CASING	6 514 868
В	CPS RACK 19" 4U	6 514 869
1	CPS FRONT PANEL	6 122 477
2	AP1200 PRINTER	6 114 632
3	BATTERY PACK (OPTIONAL)	6 311 098
4	CPS MOTHERBOARD	6 451 596
5	24V 60W POWER SUPPLY BOARD	6 111 308
6	CPS CENTRAL CONTROLLER DISPLAY	6 133 707
7	RS232 SUB D9 CONNECTOR	6 116 263
8	M16 GROMMET: D5 to D7mm	6 131 166
9	M20 CABLE GLANDS : D6 to D12 mm M20 PE PLASTIC SCREW	6 143 504 6 143 529

### Central controller electrical connections

Electrical connections are wired through the central controller MOTHERBOARD and the power supply 24V. For the CPS central controller (wall-mounted version), you must open the casing door to access the electrical panel.

Electrical connections must be done by a qualified professional. Observe all current Directives, notably the European Low Voltage Directive. Customers in France must observe standard NF C 15-100.



### **WARNING**

Contact with voltage may result in serious injury or death.

Install all equipment and complete all wiring work before turning on the power.



### **WARNING**

Improper installation can result in incorrect gas level readings or system failure.

Carefully follow all instructions to ensure proper system operation.

### Main power supply

Test the current and voltage running through a network before making any connections. Never connect the device without first disconnecting the power supply. The central controller does not have an on/off switch.

Protect the central controller from upstream current with a 4A bipolar differential circuit breaker with a type D response curve. This circuit breaker must be included in the electrical installation of the building and must be placed near of the device and must be available for the operator. On the circuit breaker will be indicated that it is the circuit breaker of the device.

**Main power supply 100-240VCA**: connector terminals L, N, and PE of the power supply 24V (Fig 3) for wall-mounted version or see connector picture 4 for rack version..

Pre-cabled wires are used to connect to the 24 VDC power supply module. The transformer output connector is also hardwired to link to the 24 VDC central controller connector and to the (optional) integrated printer for the rack-mounted version.

### **Grounding the central controller**

The central controller is intended for use in areas that meet the Class II requirements for overvoltage and degree of pollution as per EN IEC 60947-1. In order to comply with the standard, the internal ground terminal *must* be grounded (Fig 3).

### **Digital lines**

The various digital modules are connected with "Bus" connectors (Fig. 5). Recommended cable: RS-485: 2 shielded twisted pairs,  $100~\Omega$ .

One pair is used to power the module, and the other is used for communication. The cable shield or tress should be connected to the terminal:  $\underline{\ }$ 

old i Data wires and the schield wires should be cut as short as possible.

### Internal relay dry contacts

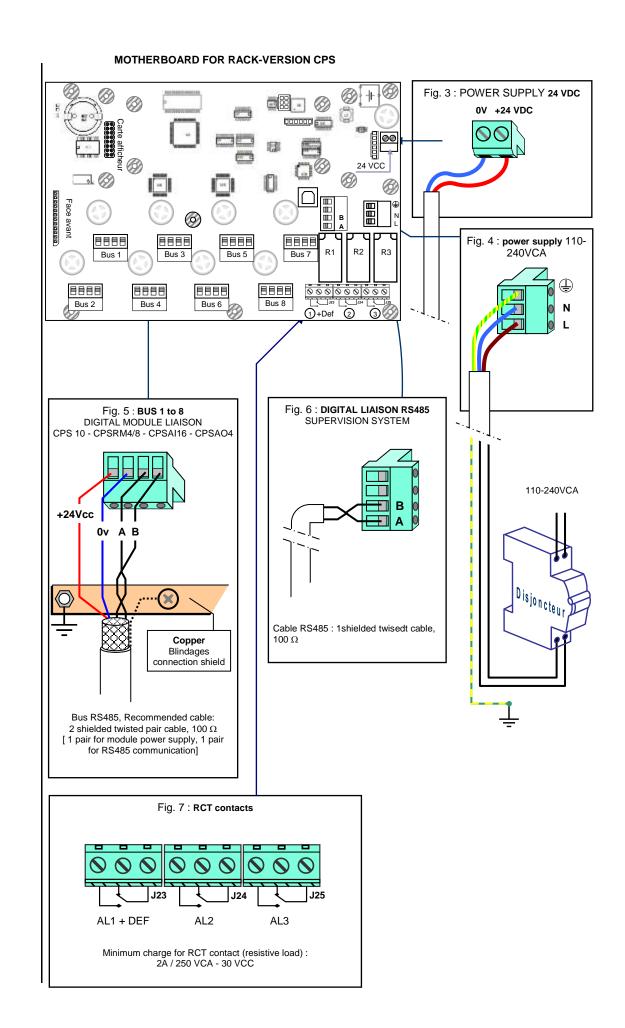
The RCT dry contacts for the 3 internal relays R1, R2, and R3 are available on the CPS central controller motherboard on connectors J23, J24, and J25 (Fig. 7). Working load: 2 A at 250 VAC, 24 VCC.

Associated alarm type: R1 (alarm/fault), R2 (alarm), R3 (alarm).

### RS-485 serial link out

Recommended cable:

RS-485 cable: 1 shielded twisted pair, 100  $\Omega$ . (Fig. 6).

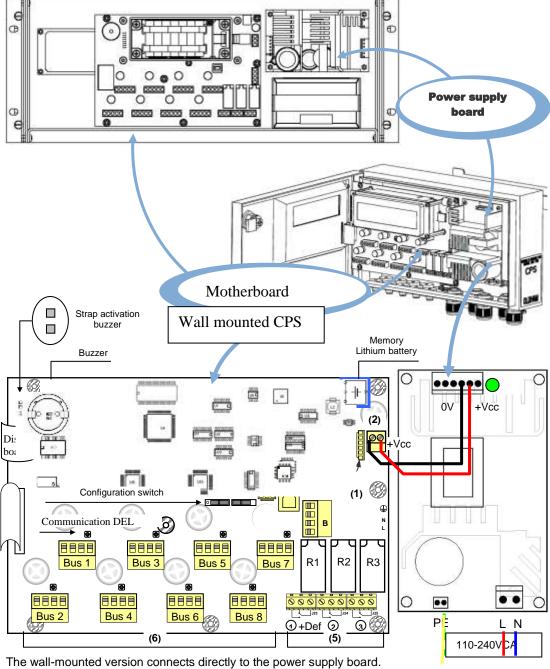


### **Overview of the Motherboard**

Part	Connector function
(1)	110-240VCA main power supply (rack version)
(2)	24 VDC external power supply connection
(3)	110-240VCA power supply for (wall-mount) power supply module
(4)	24 VDC power supply output for power supply module motherboard + integrated printer (rackversion option) power
(5)	Internal contact relay outputs (RTC) dry contacts, potential free

Part	Connector function
(6)	Digital addressable modules 8 line connectors for connecting digital modules (CPS 10 – CPSRM – CPSDI16 – CPSAO4)
(7)	RS-485 digital output links to a supervision system
(8)	USB serial interface (PC/COM_CPS connection for configuration)
(9)	RS-232 serial interface link PC/COM_CPS connection for configuration, External serial printer connection

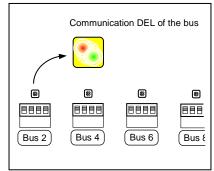
R1, R2, R3: central station shared internal relays



### Inspecting the digital buses

Bicolor (red/green) LEDs located above each line start, on the motherboard, allows for inspection of the bus links as follows:

LED appearance	Status
Red + Green LEDs lit (LEDs blink rapidly, almost imperceptibly) Orange in appearance	Normal operation. Red LED→ question Green LED ← response
Red LED blinks once per second (green LED is off) Red in appearance	Communication fault. Missing or faulting module.
Irregular blinking	Poor communication quality
Both LEDs off.	No active modules

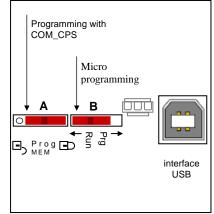


### **Mini-switches**

**Mini switch A** allows the CPS controller to download and read the user program. When the switch is in the "MEM" position (open padlock), the user program memory is accessible and the message "switch open" is displayed on screen. The CPS central controller waits to download the program from the *COM\_CPS* software. The CPS central controller goes into "shut-down" mode when mini switch A is in the "MEM" position.

When the COM\_CPS software programming is complete, the mini switch should be flipped back to the "Prog" position (closed padlock), and the central controller should be rebooted to initialize all of the newly loaded settings.

**Mini switch B** only used for the central controller's internal microprocessor. It should always be in the "Run" position.



### **COM\_CPS** Internal relay and buzzer

The CPS central controller is equipped with 3 internal **relays** [R1, R2, R3] and a shared **Buzzer**. The operating settings for the relays and the buzzer can be set with the *COM\_CPS* software (see table below).

The internal buzzer is activated when a specific program-defined event occurs (fault or alarm). All lines share relays R1, R2, and R3.

The buzzer's pitch will vary according to the alarm threshold. Alarms 1 and 2 have the same frequency. Alarms 3 and 4 have a different pitch, allowing the operator to distinguish between alarm levels.

The buzzer can be disconnected by removing the "buzzer activation strap" (J10) located on the motherboard next to the buzzer (cf -: Overview of the Motherboard).

Function / Component	Relay R1	Relay R2	Relay R3	Buzzer
AL 1	X	X	Х	Х
AL 2	X	X	Х	Х
AL 3	X	X	X	X
AL 4	X	Х	Х	Х
Module error		X	X	X
System fault*		Х	Х	Х
Out of Range and Fault	Х	X	Х	Х
Positive security		Х	Х	

<sup>\*: (</sup>System fault) alarm is triggered if there is a communication fault betweenmodules, a short-circuit in a power supply line, or a module inversion.

X: Function can be activated or deactivated

: Default configuration setting, cannot be changed by user.

### **USB / RS-232 serial connectors**

The CPS central controller is equipped with a serial port which are used to:

- download the user software (see COM\_CPS instructions);
- program the integrated micro application according to the position of mini switches on the board (factory setting).

# **I** The serial port has 2 interfaces: USB and RS-232. Only one can be used at a time.

The settings for the central controller can be modified after the program has been created. (Use either the USB or RS-232 adapter to connect the PC to the CPS central controller.

(See Chapter 7 - Program transfer).

### **USB Interface (1)**

Use a USB cable to connect the PC to the CPS central controller running the COM\_CPS application.

The USB interface emulates a serial port and is preferable to an RS-232 serial connection.

The corresponding USB driver must be installed before the PC is connected to the central measuring station (see *COM\_CPS* instructions).

### SUB-D 9 RS-232 Interface (2)

Use a cross-over RS-232 serial cable to load the user software.

RS-232 cable series reference number: **6 116 026** 

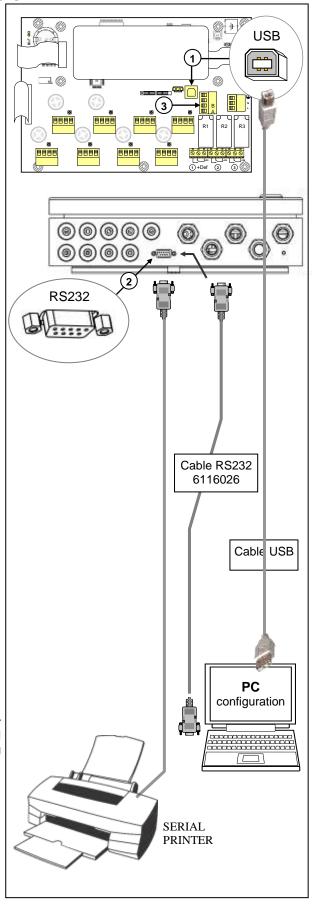
A serial printer can be permanently connected.

This would allow you to load the software via the USB interface without disconnecting the printer.

### RS-485 serial connection (3)

The RS-485 serial port (3) is reserved for the supervision system and is composed of an RS-485 interface using JBUS/MODBUS protocol.

A table containing all of the important information pertaining to the central controller can be found in the corresponding annex of Chapter 8.



### **Printer (Optional feature)**

Connection: Central controller RS-232 interface via an RS-232 serial cable.

Communication settings: 19200 Bd, 8 bit, no parity.

Event printing "on the fly."

<u>Status table printing</u> (choice of four printing schedules). For example: average readings over 20 minutes, 1 hour, or 8 hours, summary of alarm and relay statuses.

"Out of paper" functionality: no data is lost when the printer runs out of paper. Once more paper has been loaded, printing will resume where it left off.

Data flow is managed as follows: XON/XOFF Protocol

#### The printer is ON

The central controller sends data to the printer on start-up. If the printer's power supply fails or if the RS-232 cable is disconnected, data sent from the central controller will be lost.

In the event that the RS-232 cable becomes disconnected, it may be necessary to turn the printer off and on again to reinitiate data transfer.

### The printer is OFF

No data is delivered to the printer. The central controller stops sending data when the printer signals the CPS central controller that it is no longer available (Buffer is full, out of paper, or printing stopped with the ON/OFF button).

The central controller will reinitiate data transfer once the printer signals that it is available (empty buffer, or signal through the printer's ON/OFF button or online button).

### The front panel circuit

The central controller front panel circuit is equipped with:

**1 LCD display:** backlit, 2 lines by 32 characters and a pictogram line for viewing sensor readings and the zone in question, various test point data, settings, events, etc.



**3 lights** on the front panel of the central controller (green for power, yellow for errors, and red for exceeding thresholds) serve as constant system status indicators.

**7 keys** to select on-screen information and/or validate certain operations via menus. The menus are available in English, French, German, Spanish and Dutch.

### **Display Screen**

# $\odot$

No alarms or errors



Icon associated with one or more alarm icons indicates (by blinking) that the associated alarm is an averaged alarm.



SOLID = instantaneous alarm 1 BLINKING = averaged alarm 1 (takes priority over solid state)



SOLID = instantaneous alarm 2 BLINKING = averaged alarm 2 (takes priority over solid state)



SOLID = instantaneous alarm 3 BLINKING = averaged alarm 3 (takes priority over solid state)



SOLID = instantaneous alarm 4 BLINKING = averaged alarm 4 (takes priority over solid state)



SOLID = stable signal in hysteresis interval (calculated over 1 minute)



SOLID = signal increased in relation to the minute before BLINKING = Exceeding the scale (takes priority over solid state)



SOLID = signal decreased in relation to the minute before BLINKING = Negative fault (takes priority over solid state)



SOLID = buzzer on



SOLID = calibration underway



SOLID = LS (low speed) relay control active



SOLID = HS (high speed) relay control active



SOLID = Error



SOLID = mains power supply OK BLINKING = battery or mains power supply problem

### **Keys**



Key

Keys primarily used to modify values (ex: line number)



Keys primarily used to navigate menus or to change variable current (ex: go from line number to sensor number)



Key used to validate a menu or an input that would alter system operation. (ex: activation of a relay)



Key used to return to a previous menu screen or to cancel a selected value before it has been validated.



Key used to acknowledge a locked alarm (programmed for manual acknowledgement) or to dismiss a buzzer relay after its holding time, even if an alarm is still active.

### Lights



**Green LED:** power supply status indicator SOLID = OK

BLINKING = power supply problem (no power to main or problem with the battery pack)

**Orange LED**: indicates the presence of one or more faults.

Red LED: signals the presence of one or more alarms.

### **Alarm thresholds**

Six alarm thresholds can be programmed and adjusted for each sensor:

Alarm 1, Alarm 2, Alarm 3, Alarm 4, Out of Range and Fault.

#### Alarms 1 - 4 can be:

- Instantaneous:
- delayed (0 to 3,600 seconds);
- averaged (period of 1 to 480 minutes).

This makes it possible to calculate STEL and TWA values.

So, for example, you could choose to activate Alarm 1 if the average calculated levels over a period of 8 consecutive hours exceeded 50 ppm, and Alarm 2 if average levels over a period of 10 minutes exceeded 100 ppm, and Alarm 3 if the instantaneous reading exceeded 200 ppm.

Averaged alarms are only triggered at the end of a complete time interval.

If the line or the detector module stops, average value calculations are halted and will only begin again once the line or the detector module has been reactivated.

Both the instantaneous and averaged alarms can be set to trigger on an increasing value (rising edge) or on a decreasing value (falling edge).

- Rising edge: alarm is activated when levels increase. Use this option for sensors measuring Explo, CO, H<sub>2</sub>S, etc.
- Falling edge: alarm is activated when levels decrease. Use this option for O<sub>2</sub> sensors, for example.

Out of Range alarm: can activate an alarm, a relay, or an LED.

**"Verification" option**: this option is activated for explosive gases. When a "verification" alarm occurs, the level displayed will be frozen at the maximum value until it is acknowledged (manually or automatically) and on the condition that the gas levels have fallen under the alarm threshold.

Example of ventilator command functionality for CO/NO detection

Alarm threshold	CO (ppm)	NO (ppm)	RESPONSE
Alarm 1	50	25	Ventilators start on low speed
Alarm 2	100	50	Ventilators go to high speed
Alarm 3	150	75	Max speed ventilation + alarm lights in the surveillance area
Alarm 4	200	100	Visual & audible alarms + restricted area access + evacuation orders for individuals in the area

### Alarm acknowledgement

Alarms can be rearmed in two ways:



**Manual acknowledgement:** the audible alarm can only be dismissed after the "Acknowledge" button on the CPS central measuring controller has been pushed; or

**Automatic acknowledgement:** the audible alarm will be automatically dismissed once the alarm condition has ended.

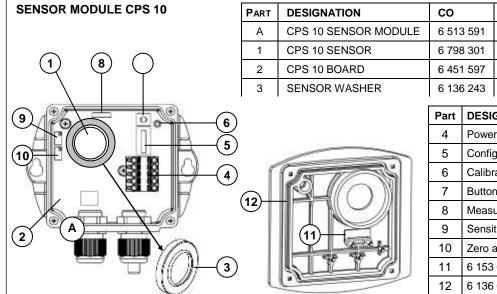
If an alarm is triggered, a corresponding message will appear on the screen, an audible alarm (BUZZER) is activated, and the red LED on the front panel is illuminated.

Touching the "Acknowledge" button once will remove the message from the screen and will turn off the BUZZER.

Touching the "Acknowledge" button a second time will re-arm the programmed alarms. These alarms will not turn off until the concentration of gas falls below the threshold.

# **Chapter 4** Digital Modules

### **View of Digital Modules**



	ı	1 1	
Part	DESIGNATION		
4	Power suppl	y & network connector	
5	Configuration	n switches (Adresses)	
6	Calibraton LED		
7	Button [sensor replacement]		
8	Measurement connector [sensor replacement]		
9	Sensitivity adjustment [sensor replacement]		
10	Zero adjustment [sensor replacement]		
11	6 153 046	CPS 10 Magnetic switch	
12	6 136 052	D2 line washer (qty: 0.316)	

NO2

6 513 593

6 113 332

6 451 599

6 136 243

NO

6 513 592

6 113 331

6 451 598

6 136 243

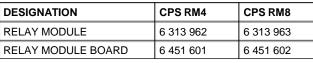
**EXPLO** 

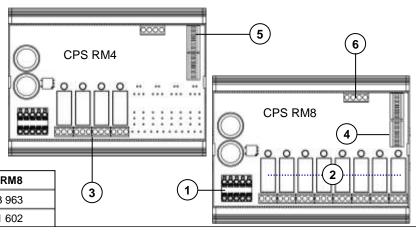
6 513 594

6 451 600

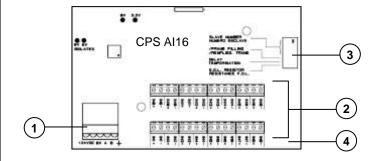
### **RELAY MODULES CPSRM4-CPSRM8**

Part	DESIGNATION
1	Power supply & network connector
2	Programmable relays ( 8 or 4 )
3	potential free RTC output contact
4	Safety switch + or - relays
5	Configuration switches (Adresses)
6	Logic Input terminals (2 Inputs)



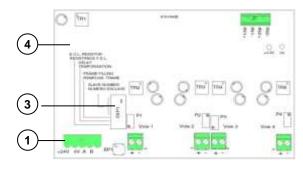


### **LOGIC INPUT MODULE CPS AI16**



DESIGNATION
Power supply & network connector
Logic input terminal (16 Inputs)
Configuration switches (Adresses)
Module board

### ANALOG OUTPUT MODULE CPS AO4



DESIGNATION	CPS AI16	CPS AO4
MODULE	6 313 964	6 313 980
MODULE BOARD	6 451 603	6 451 614

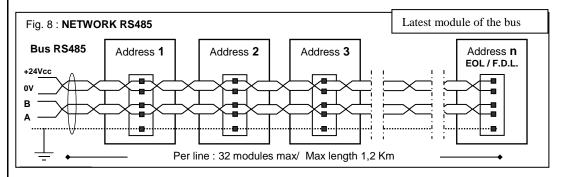
### **Connecting Digital Modules**

### General topology of the RS-485 network

Modules are connected in "parallel" in the RS-485 network, comprised of a 1 twisted pair cable for signals, 1 or more pairs to supply power to the modules, and 1 shield wire.

A 120  $\Omega$  end of line resistor (**EOL RESISTOR**) should be placed at the last module in the line, at the end of the bus (see Chapter 4 - End of Line Resistor).

The modules are equipped with a double connector, which can be split to easily connect conductors and also allows you to isolate the module while maintaining line continuity.



### Wiring the digital network

The sensor module has two cable glands. One connects to the input wire, and the other connects to the output wire which is routed to the next module.

The modules should be wired with RS-485 shielded twisted pair cable, with a normal impedance of 100  $\Omega$ , of at least 0.22mm² in diameter. +24VDC, 0V A and B terminals are linked to +24VDC, OV terminals A and B in other modules in the line, and then linked to the connector corresponding to the central controller. The cable shield should be connected to a ground terminal marked with the following symbol: (Fig.9).

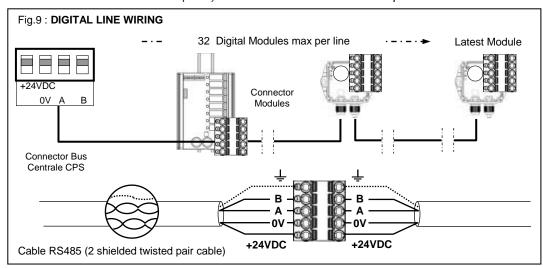


An improper installation can cause incorrect gas level readings or system failure.

Do not run cable near equipment such as motors, transformers, or any lines generating a large magnetic field.

Always check to ensure that the cables are completely separated from other circuits.

1 Do not leave any stripped wire ends exposed. To guard against electromagnetic disturbances, the data cables and the screen (tress) cables should be cut as short as possible



### **Configuring the communication settings**

### Slave address

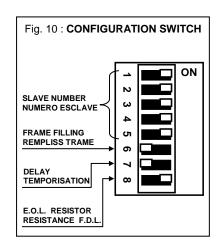
All modules in a line should be identified with a unique slave number. Switches 1-5 on the **configuration Switches** unit (Fig. 10) contained in each module, allow you to set a binary numerical address (1...32).

Possible combinations are listed in the address table below.

**Notes**: The physical address of a module (1...32) should be identical to the address recorded in the central controller configuration program with *COM\_CPS*.

When replacing a module, set the configuration switches in the new module to the same position as those of the module being replaced.

**1** Switches 6 (FRAME FILLING) and 7 (DELAY) should be in the OFF position (unused options).



### **End of line resistor**

The last module in each line should be equipped with an end of line resistor. ).

**1** This switch should be in the OFF position for all other modules in the line.

### **Address Table**

SS	SWITCHES								
Slave Address	ON = 1; OFF = 0								
S Ac	1	2	3	4	5				
1	1	0	0	0	0				
2	0	1	0	0	0				
3	1	1	0	0	0				
4	0	0	1	0	0				
5	1	0	1	0	0				
6	0	1	1	0	0				
7	1	1	1	0	0				
8	0	0	0	1	0				
9	1	0	0	1	0				
10	0	1	0	1	0				
11	1	1	0	1	0				
12	0	0	1	1	0				
13	1	0	1	1	0				
14	0	1	1	1	0				
15	1	1	1	1	0				
16	0	0	0	0	1				

SS	SWITCHES						
Slave ADdress	ON = 1; OFF = 0						
S AL	1	2	3	4	5		
17	1	0	0	0	1		
18	0	1	0	0	1		
19	1	1	0	0	1		
20	0	0	1	0	1		
21	1	0	1	0	1		
22	0	1	1	0	1		
23	1	1	1	0	1		
24	0	0	0	1	1		
25	1	0	0	1	1		
26	0	1	0	1	1		
27	1	1	0	1	1		
28	0	0	1	1	1		
29	1	0	1	1	1		
30	0	1	1	1	1		
31	1	1	1	1	1		
32	0	0	0	0	0		

### **CPS 10 Detector Module**

The CPS central controller accepts 10 types (or 10 different configurations) of sensors. The type of sensor used in the module depends on the gas being monitored. Electrochemical sensors are used to measure CO, NO, NO<sub>2</sub>, for example, while catalytic sensors measure gases such as GPL, CH<sub>4</sub>, and H<sub>2</sub>).

### **Available Detector Types**

Sensor			Measur	ement	Sensor life expectancy
Carbon monoxide	CO	:	0 300	ppm	36 months
Nitric oxide	NO	:	0 100	ppm	24 months
Nitrogen dioxide	$NO_2$	:	0 30.0	ppm	24 months
Methane	CH <sub>4</sub>	:	0 100	% LEL	48 months
Liquefied petroleum	LPG	:	0 100	% LEL	48 months
Hydrogen	$H_2$	:	0 100	% LEL	48 months

#### Sensor module fault

In the event of a sensor module fault, gas levels are no longer taken into account, and all alarms are cancelled, except for the negative threshold (or fault) which is activated. Average values are no longer taken into consideration and the calculation of average values is paused.

If a sensor faults, it can be replaced while the central controller is still running (hot swap) without replacing the detector.

### **Detector settings**

The following settings apply to each type of detector:

- The abbreviated name to be displayed on the central controller: NO, CO, CO<sub>2</sub>...
- The name of the gas: Carbon monoxide, Nitric oxide, Oxygen, Methane ...
- **Unit:** ppm, LEL, %v/v ...
- Range with display format: 100, 10.0, 1.00, ...
- Actionable thresholds:
  - o 4 instantaneous thresholds: 0-100% measuring range,
  - 4 averaged thresholds: 0-100% measuring range, (time interval programmable from 1 to 480 minutes).

If the operating time is inferior to the averaging time interval, the averaging time interval is ignored.

An instantaneous threshold is associated with an averaged threshold to generate an alarm. These two thresholds can be set to trigger on the rising edge (increasing alarm) or the falling edge (decreasing alarm).

### Alarm delays ( 0s to 60 min ):

Each of the 4 alarm thresholds can be delayed. If gas levels are in excess of an alarm threshold for an amount of time inferior to the programmed delay, the alarm will not activate.

The alarms can be acknowledged automatically once the alarm is turned off, or manually when the gas levels are once again under the threshold.

### Fault thresholds:

- o "underscale" negative signal (exceeding the lower threshold): -10% of the range.
- o "SUP" out of range (exceeding the upper threshold): +120% of the range.
- o "Verification" for all explosive gas sensors, in case an LEL threshold is passed, the SUP alarm remains on even after levels fall under the threshold. The fault alarm is also triggered.

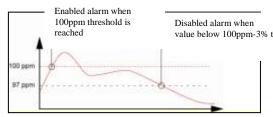
### Hysteresis:

Max. 1% of range. Default value = 0%.

### Example (see opposite page):

Measurement range = 300 ppm; Alarm = 100 ppm; Hysteresis (1% of range) = 3 ppm

Level at which alarm can be dismissed = 97



### **External relay module**

The relay module is available in two versions: CPS RM4 (with 4 relays) and CPS RM8 (with 8 relays). It also has two logic inputs (LI) which can be activated.

In maximum configuration, the CPS can manage 256 relays (ex: 32 modules with 8 relays each). For more information about the logic inputs: see: Logic inputs module.

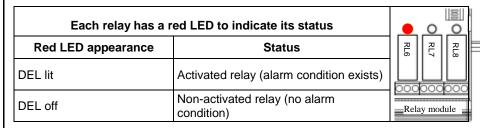
The relays are individually programmable. The operation of each relay depends on its configuration and its function.

Each of the 6 sensor alarms [AL1 - AL2 - AL3 - AL4 - Out of Range - Fault] can control one or more of the 256 relays. Several events can be linked to one relay.

### In case of a module relay fault, all relays of this module are restarted.

The CPS central controller will change the relay status unless they belong to a different module type. Restarting will resolve the problem.

### **Relay status lights**



### "Positive/negative" relay security

In addition to switches of CONFIGURATION, RELAY MODULES INCLUD SWITHCHES OF POISITVE AND NEGATIVE SECURITY CONFIGURATION. Flip the switch to **ON** (positive security) or **OFF** (negative security) as desired. Each switch acts on its corresponding relay (switch 1  $\rightarrow$  relay RL1, switch 2  $\rightarrow$  relay RL2, etc.). (Fig. 11).

Note: Only switches 1-4 are active in the CPSRM4 module. Fig. 11: « POSITIVE / NEGATIVE » RELAY SECURITY CONFIGURATION (LI) 0000 SWITCH Relay module **CPS RM8** ON CPS RM4 [1 à 4] 8 Red DEL: Relay status N ON = SECU + CPS RM8 [ 1 à 8 0 ယ 4 RL6 RL2 RL3RL4 RL5 RL8 RL7 G တ 7 ω **Output contact Relay** Logic input (LI) Minimum charge for contacts 2A / 250 VAC (Load charge)

### COM CPS

### **Relay configuration**

### "Normal" relays

The relay is activated when an alarm occurs and is deactivated when the alarm condition ends.

The variables acting on a relay in alarm status are:

- Alarm delay
- Automatic / Manual acknowledgement
- Forced state change via the CPS menu
- Forced state change via a logic input command

### "Buzzer" relays

The "Buzzer" relay is used to control an audible alarm.

It can be re-armed with the [ **Acknowledge** ] key on the central controller, even if the alarm condition has not changed.

The occurrence of a new alarm will reactivate the relay and reset the delays.

The "Buzzer" relay can be automatically dismissed before the end of the alarm with a 15 to 900 second delay (standard setting for "Buzzer" relays) or manually, even if the alarm condition has not changed. It can be configured with a minimum operating time of 1 sec. to 5 min.

The variables acting on a relay after an alarm has occurred are:

- Alarm delay
- Automatic / Manual acknowledgement
- Forced state change via the CPS menu
- Forced state change via a logic input command

### Alarm and/or "Buzzer" relay delays

Alarm d	lelays	Relay delays
		"Buzzer modes"
Instantaneous Alarms	Averaged Alarms	Min. activation time: 0 300 seconds
1 3600 seconds	1 480 minutes	Acknowledgement time: 15 900 seconds
Standard settings for	r each sensor type	Standard settings for all "Buzzer relays"

### "LS/HS" Relays

Low speed (LS) relays and high speed (HS) relays are always used together, allowing you to control a parking facility ventilation system at two speeds.

**LS** (low speed): The relays are designed to control slow ventilator speed (star-triangle configuration for a two-speed ventilator).

**HS** (high speed): The relays are designed to control high speed ventilator speed (star-triangle configuration for a two-speed ventilator).

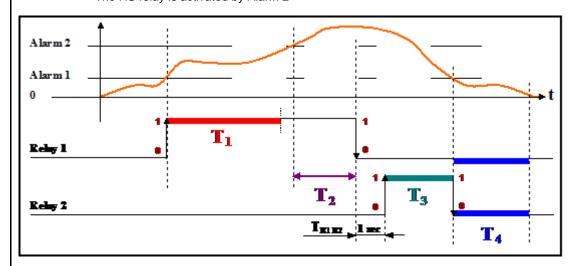
The working logic of the relays defined hereafter, takes into consideration the start-up and shut-down intervals during which very high levels of current may occur, capable of damaging motor windings if phases occur in the incorrect sequence.

### "LS / HS" Operation

Requirements: Alarm level 1 < Alarm level 2

The LS relay is activated by Alarm 1

The HS relay is activated by Alarm 2



Phases		Action operation	Default Delay*
T <sub>1</sub>	Min. duration LS operation Adjustment(s): [ 1 32767 ]	Minimum duration, in seconds, during which the ventilator operates at low speed	5 min.
T <sub>2</sub>	HS operation delay Adjustment(s): [ 2 32767 ]	Minimum duration for Alarm 2, after which the ventilator switches to high speed	15 min.
T <sub>R1</sub>	LS/HS transition time 1 second (cannot be changed)	Transition time between Relay 1 and Relay 2 is 1 second (standardized throughout the central controller)	1 sec.
<b>T</b> <sub>3</sub>	Min. duration HS operation Adjustment(s): [1 32767]	Minimum duration, in seconds, for the ventilator to operate at high speed. HS relay deactivated if Alarm 1 condition ends	10 min.
<b>T</b> 4	LS-HS stop delay Adjustment(s): [ 1 32767 ]	Duration, in seconds, after low or high speed ventilator operation has been stopped, before the ventilator can be restarted at low speed.	10 min.

Time values  $T_1$ ,  $T_2$ ,  $T_3$  and  $T_4$  can be modified. When the "Sensor simulation" menu is used (see the chapter on the maintenance menu/simulation on page 43) the times are decreased, by default, to 12 seconds, 24 seconds, 36 seconds, and 24 seconds, respectively.

**Note:** An underscale alarm (= fault) activating a LS or HS relay will force the relay into HS position (with respect to the defined time).

### "Forced ventilation" function

This is a forced relay state change via the CPS menu. This function allows you to block or release the HS (high speed) command at specified times.

Forced relay state change via a logic input command

In both cases the response is immediate and priority safety settings are maintained: HS takes precedence over LS, and both relays are shut-down if there are contradicting signals.

### **Logic Input Module**

COM CPS

This module contains 16 logic inputs, linking priority commands, such as fire extinguishers directly to the central controller.

A maximum of 224 total logic inputs across all modules can be activated.

**Example 1:** 112 modules having 8 relays each, with activated inputs.

**Example 2:** 7 modules with 16 logic inputs with activated inputs.

Each input can override all other commands to activate or block up to 256 relays.

### **Priority inputs**

Two levels of input priority can be managed on each module with the COM\_CPS software.

Priority inputs have control of the other inputs (all of the non-priority inputs are "blocked" when a priority input is activated).

In the event that two different inputs of the same priority level send contradicting orders, the relay is shut-down.

In the event of a fault, the inputs are set to zero.

CPS AI16

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# COM\_CPS Analog Outputs Module

This module is comprised of 4 opto-isolated 4-20 mA analog outputs which can be individually activated or deactivated.

Activated: the output analog signal (4-20 mA) varies, according to the input

Deactivated: the analog output signal will be frozen at 0mA, regardless of the input signal.

Several events can be linked to one output. In this case, the largest analog value will be recopied onto the analog output.

The output module also has two logic inputs (LI), identical to those on the "Logic input" module.

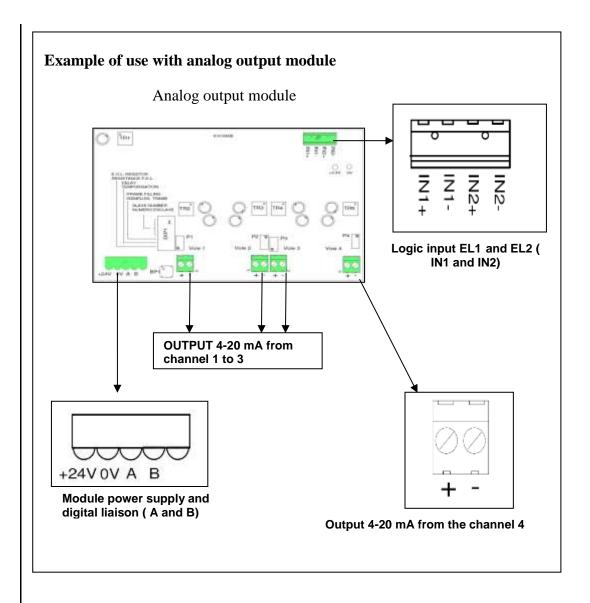
A "slave address" for the module can be set with the "DIP" switch (DIP1).

An analog output OFF command from the central controller corresponds to 4 mA.

An analog output ON command from the central controller corresponds to 20 mA.

Connections:

# Analog output module



#### **Detailed Menus Chapter 5 ©AAAAA→7¥41/1**⊗⊗⇔ **Menu Tree** Start Display Cycle **Starting** If a button is not pushed during 10 min, the display mode, determined by fault in the menu < System > < Start Config > is automatically used ESC Scan& Sensor **Events** Relay Status **Print** Display Display status 4-20mA Control ESC OK Cyclique Événements ESC OK **Event Print** ON/OFF printer Module status All module **Printing** ESC System status status of line OK Activation Line, Date and Hour Start config **System** Module, relay ESC [XXXX acces] (Activate : Line - module relays - 4-20mA output) OK Simulation Module Bus default Maintenance reset **Maintenance** Control ESC OK OK OK ESC [XXXX acces] ESC Version COM\_CPSF One sensor Relay status 4-20mA Micro Free time output ESC OK ESC [XXXX acces] Infos Modules OK OK OK POWER SUPPLY [xxxx acces] Visualisation Ref. Module Status CRC DAY NUMBER retry Rate of fault Installation CPS Reset retry overscale Measures SINCE LATEST Reset for calibration module CALIBRATIONT Temperature ESC → ESC ESC calculation and ESC overscale Page 36 CPS - User Manual

## Start-up Phase

No faults or alarms are processed during the first minute after start-up. During this phase, the central controller runs a Checksum test (1), a RAM test (2), a line start-up (3) and a module mapping test with a program stored in its memory.

Voltage builds progressively in the lines. Progress bars show the overall progress for line power-up.

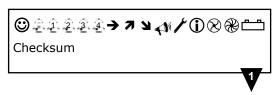
Only the power-up of activated lines is shown (identified by a diamond "♦" during the initial power-up phase, and by a black square "■ " at the end.)

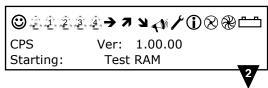
An exclamation point "!" indicates a short-circuit line fault. The line can be reactivated through the menu system.

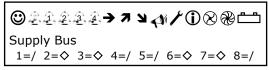
Next, a sensor stabilization phase occurs (4) during which time, the alarms are deactivated.

An inspection phase immediately follows in order to verify that the configuration program set with the *COM\_CPS* software correctly maps to the modules installed and activated.

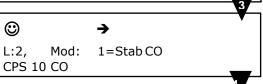
If no errors are found, the program runs normally. If errors are detected, the modules in question will be flagged as faulting.









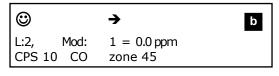


After the start-up phase, the screen will display information pertaining to the selected mode: events (a) or cyclic (b). The central controller begins to process data coming in from the various modules.

In cyclic display mode, when no alarms are triggered the levels from each sensor are displayed on the first line of the display screen.

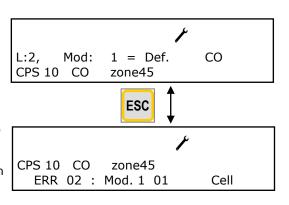
In case of a power outage, the program configuration will be saved. When the controller is turned on, the last program installed by *COM* CPS will be loaded.





If a sensor faults, the message "Def" will replace the reading value. If the power supply is interrupted within a line, the two points in front of that line will blink. Identify the problem by touching the [ESC] key to display the error message.

If the gas level exceeds a high or low threshold, "Ovs" will appear on the display screen where the value for that sensor would normally appear. This message will display simultaneously with a blinking arrow (pointing up or down, depending on the situation).



#### **Control Menu**

#### **Normal Display**

Alarm pictograms will appear and disappear in along with the alarm conditions detected by a given sensor. The display shows gas level readings, which may not always be identical to the status of a relay. Under normal conditions, alarm pictograms reflect relay status.

**Example:** LS and HS relays are configured to run on a delayed trigger. Pictograms do not take this delay interval into consideration. So it is possible that the LS or HS relay is on, while the alarm pictogram does not display on screen, due to the alarm delay.

#### Cyclical display

This menu allows you to view all of the activated sensors on screen, at a display rate of one sensor every two seconds.

#### **Event display**

This menu allows you to view the status of all sensors in alarm mode, faulting, or in calibration, at a rate of one sensor every two seconds.

#### **Sensor Display**

This menu allows you to freeze the display on a specific sensor by selecting the line and the module number (The program automatically selects active sensor modules).

Touching the [ **OK** ] key once will bring up the sensor name, the abbreviated gas name, the gas level and unit of measure (ppm, % LEL, \$v/v).

If the sensor is faulting, "Def" will display in place of the level reading.

Select the line or the sensor (if appliable) using the  $\lceil \P \rceil \lceil P \rceil$  (horizontal) keys.

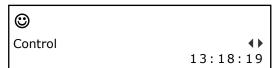
Select the line number or the sensor number (if appliable) using the [  $^{\blacktriangle}$  ] [  $_{\blacktriangledown}$  ] (vertical) keys.

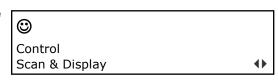
Press [OK] to select the sensor.

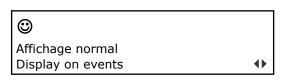
Press [OK] a second time to display both the gas reading level and the 4 averaged readings if average readings were activated. If averaging was not activated, < \*\*\* > will display on screen.

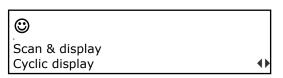
If a communication fault occurs, the value will be replaced by < \*\*\* > and the averages will stop on the last calculated value.

For all other faults, the gas level will be displayed in order to help the user identify the problem.

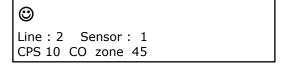


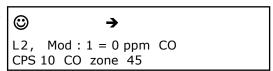


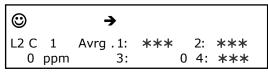


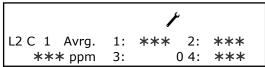












```
L2 C 1 Avrg. 1: *** 2: ***
-37 ppm 3: -1 2 4: ***
```

#### **Events**

This menu can be used to search through a history of the most recent 1,200 events. A record of these events can be printed. State changes are recorded in the history.

If Alarm 1 ends and Alarm 2 is triggered, AL2 ON will be recorded.

#### **Examples**

- (a) The shut-down of a line causes the shut-down of alarms and relays for that line.
- (b) The "fault" alarm is triggered for module 3, line 1.

#### Other examples:

Module 2, line 8 turned on

30/06/06 (day/month/year) 14:40:36 L:8, Mod:02 Module ON

Alarm 2 triggered

30/06/06 14:49:37 L:8, Mod:02

Alarm 2, OFF  $\Rightarrow$  ON

State change for Relay 2 (command relay)



30/06/06 14:49:37 L:8, Mod:29

Relay 2 Normal ON <u>Conditions for Alarm 2 end</u> 30/06/06 14:51:03 L:8, Mod:02

30/06/06 14:51:03 L:8, Mod:02 Alarm 2, ON  $\Rightarrow$  OFF

Acknowledgement action

25/ 06/ 07 19:06:02 Line 2 OFF

30/06/06 14:55:21.

**ACKNOWL** 

State change for Relay 2 (relay shut-down)

30/06/06 14:55:21

Relay 2 Normal OFF

#### **Relay Status**

This menu displays the status of a relay in a given module. Increments for the preceding and following modules in the line are automatically calculated.

Display the status for the selected relay by pressing the [OK] button. This screen will show the module, its mode of operation (Normal, Buzzer, LS, HS,...) and its status (ON, OFF).



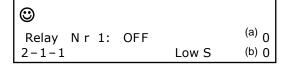
**©** 

Line: 2 MoDule 1 Relay Module Level-1

(a): (LS / HS) - Delays

(a): (Buzzer Relay) – Acknowledgement time

(b): (Buzzer Relay) - Min. activation



#### 4-20 mA Output Status

This menu displays the outputs for the selected module. The value is displayed in mA.

Multiple inputs can be linked to one output. In this case, the largest analog value will be recopied onto the analog output.



Activated analog output: the 4-20 mA output signal varies according to the input.

Deactivated analog output: the 4-20 mA output signal will be frozen at 0mA, regardless of the input signal. The output current for each channel will vary between 0 and 24.5 mA.

#### **Printing**

#### "System status" Report

This menu is used to initiate the printing of system status reports. The second part indicates the fault status for all of the modules in each line. Each hexadecimal number corresponds to a module, with Module 1 being on the left, and Module 32 on the right.



0 = OK

- 1 = Communication error
- 2 = Module recognition error
- 4 = Fault triggered by a module fault word.
- X = (no programmed module)



If the system detects an abnormality in either the name or the range of a gas, the letter N will blink on the screen

#### "Status for all line modules" Report

Sensor module: the printed reports will contain both the reading and the averages if averages are activated.

Relay module: the printed reports will contain the status of each relay and of each relay's logic inputs.

Logic inputs module: the printed reports will contain the status of all logic inputs.

#### "Module status" Report

Prints the status of every module in the selected line. See previous paragraph.

#### "Printer On/Off" Report

Use the [ riangleq ] and [ riangleq ] keys to activate or deactivate the printer.

When the printer is activated, the **COM\_CPS** cannot be used to for reading or configuration. The configuration mini-switch (A) must be placed in the open padlock position to enable communication between the serial port and the **COM\_CPS** software (cf "Programming mini-switches").

#### "Event" Report

This feature allows you to print all of the most recent events stored in memory (up to 1,200).

**Calibration Report:** The calibration data for a sensor is only printed at the end of the calibration process. The record will consist of a title, the line number and module number and 6 readings if a complete calibration has take place:

Calibration1 Sensor 4 01 CO Xo1 = 00004 Xo2 = 00000 Xo3 = 00000 Xf1 = 00095	Zero value before starting procedure Zero value Zero value after procedure Value of the concentration of calibration gas
Xf1 = 00095 Xf2 = 00100	Value of the concentration of calibration gas  Value of the response to the gas
Xf3 = 00100	Value of the reading at the end of the procedure

#### Acces code

An access code is required to access certain menus. The access code is made up of 4 hexadecimal numbers. If the wrong code is entered three consecutive times, the code will be deactivated until all menus have been exited or until after 10 minutes of inactivity. The **COM\_CPS** software can be used to modify the access code.

The default access code is: 1 0 0 0

## **System Menu**

#### Line, Module, Relay Action

#### Line activation

The selected line is displayed along with its number and name.

To go to a different line, use the

[ ▲ ] [ ▼ ]. Change the status by pressing the [ OK ] key, and then pressing the [ ◀ ] [ ▶ ] keys, followed by [ OK ].

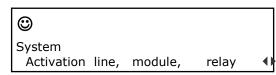
If the line is shut-down, the line number will flash intermittently with a cross sign. If the module does not correspond with the CPS central controller COM\_CPS-created program, its status is reported as faulting.

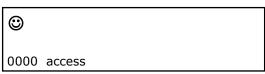
**Notes**: If the line is shut down by the COM\_CPS software, it is impossible to turn it on.

A line is fully activated approximately 5 seconds after start-up.

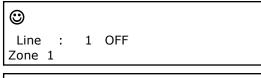
A thermal fuse protects the line's power supply from short-circuits. Should a short-circuit occur, a fault word will appear in the menu and an error message will be recorded in the event log. After the short-circuit, the line must be reactivated via the menu.



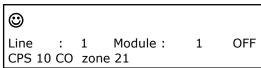












#### Relay activation

Use the same "Relay Status" menu to select a relay. After pressing [ **OK** ] to select the relay, you have three options:

< Normal > = Relay functions normally (triggered by alarms)

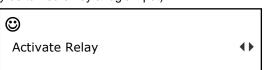
< ON > = Relay in forced operation (can only be shut-down by a logic input)
< ON > = Relay in forced shut-down (can only be turned on by a logic input)

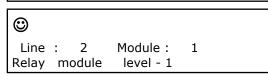
#### Special case: LS and HS relays

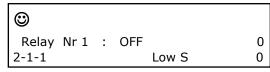
For safety reasons, deactivating a LS or HS relay via the CPS central controller shuts down of the two relays and restarts their timing devices.

If a logic input or a command from the CPS central controller activates a LS or HS relay, the relay will be activated. The relay's activation time is set to the maximum value. In other words, the forced relay shut down ends when logic inputs no longer command the relay or after the end of an alarm condition which could control the relay.

Similarly, if an alarm triggers a HS relay, a LS relay cannot be activated.







The forced activation of a HS relay takes priority over scheduled HS freezes.

#### **Activating analog outputs**

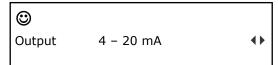
Choose the 4-20 mA output for the selected module. Pressing [ OK ] will force a start-up or shut-down for the 4-20 mA output.

- The shut-down freezes the output at 4 mA.
- The start-up freezes the output at 20 mA.

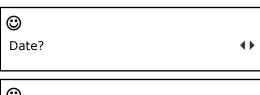
#### **Date and Time**

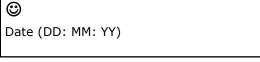
△ Changing the time settings will reinitialize LS and HS delays!

**Example**: If the HS relay is activated and the time is changed, the HS relay will stop so that the LS relay can operate according to the predetermined delays.











#### 0 3/ 0 7/ 0 7

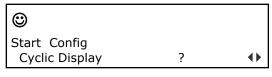
## **Start-up Configuration**

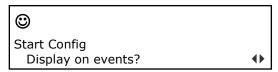
This menu is used to select which menu will display by default upon start-up and after 10 minutes of keyboard inactivity.

The two menu options are:

Cyclical Display and Event Display.







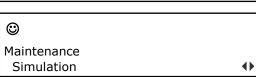
#### **Maintenance Menu**

#### Simulation

This menu is used to simulate the alarms for a particular sensor module or to temporarily activate one or more relays (or outputs). After exiting the simulation menu, the sensors and relays (excluding LS and HS relays) revert to their prior state.

Enter the access code by using the [ $^{\land}$ ][ $_{\checkmark}$ ] and [ $_{\checkmark}$ ][ $_{\backprime}$ ] keys.







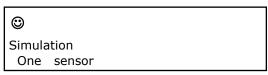
#### Sensor simulation

Select the sensor module you wish to test. Next, select the delay between each of the alarms to be activated (1-59 sec.). Validate your selections by pressing [ **OK** ].

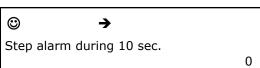
The central controller will increase reading levels until they exceed the thresholds for all activated alarms in ascending order +/- hysteresis. During the simulation, the theoretical values are displayed on screen.

During this phase, the other sensors are shut down. However, forced-state lines, modules and relays remain active.









#### **Relay Status Simulation**

Select the relay module for the relay you wish to test, then the relay you wish to activate.

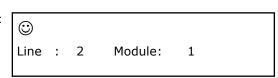
Use the same "Relay Status" menu to select a relay. After pressing

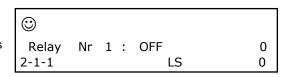
[  $\mathbf{OK}$  ] to select the relay, you have three options:

- < Normal > = Relay functions normally
  (triggered by alarms)
- < ON > = Relay in forced operation
  (can only be shut down by a logic input)
  < OFF > = Relay in forced shut-down
  (can only be shut down by a logic input)

After exiting this menu, the relay will revert to its original state.





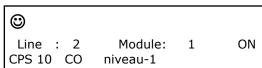


#### **Analog Output Simulation**

#### **Module Verification**

Inspection of all of the parameters relating to a module with a *communication fault*.





E = Status word

**D** = Fault word

C = Start-up config. word

**M** = Level for sensor modules or State for logic inputs

T = Temperature

**Cal** (Value) = Concentration of gas used for calibration

**ID** = Module fault

Displays useful variables and operating time according to the module type:

(Value) = line voltage

**R** = Relay status (hexadecimal)

(Value) J = Number of days since last calibration.

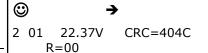
 $\mathbf{0} = X0$  for sensor modules.

**f** = Xf for sensor modules.

**U** = Wear rate for sensor modules.

CRC = (Cyclic Redundancy Check)

Software version for the module program.



**Dep.** (value) H = Time (in hours) during which the sensor exceeded the scale.

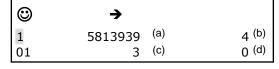
**Ref**: (Value) = Sensor reference.

**Retry:** (plural form, *retries*) – attempt(s) at retransmission. Used to control the quality of communication with the modules.

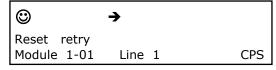
**(a):** represents successful transmission attempts. This number increases continually and should be as large as possible.

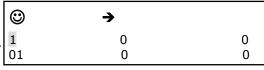
**(b), (c), (d):** represents next 3 successive retransmission attempts, if necessary, following a failed attempt. In the event that the 1<sup>st</sup> attempt (1) fails, a 2<sup>nd</sup> attempt (b) will occur, then a 3<sup>rd</sup> (c), and 4<sup>th</sup> (d). The number and the level of saved attempts is indicative of the transmission quality. A large number, on level 3 or 4 is due to poor transmission.

Reinitialize "retries" by selecting the "Reset retry" menu.



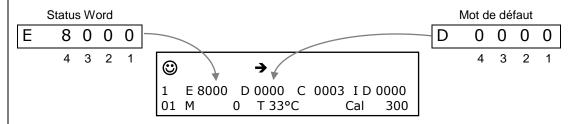






Any module fault generates an event, which is identified by a number (hexadecimal coding) corresponding to the fault type. The number at the end of the second line displays the module error.

The [ $\P$ ] [ $\blacktriangleright$ ] keys can be used to change the scroll mode: in normal mode, all events saved to memory are displayed; in default mode, only the faults saved to memory are displayed.



#### Fault word

4	3	2	1
1 = Def Flash	1 = Def Temp. Min	1 = Def Zero calibration	1 = Def ROM main memory
2 = Def sensor	2 = Def Temp. Max	2 = Def Sens. calibration	2 = Def RAM
4 = Low line power	4 = Def Meas. Min	4 = Def Zero Sensor replacement	4 = Def Battery
8 = high line power	8 = Def Meas. Max	8 = Def Sensitivity. Sensor replacement	8 = module parameter does not correspond to the module card

Sample fault word: 00A0 = Def Sens. calibration + Déf Sensitivity. Sensor replacement (A = 10 in hexadecimal = 8 + 2)

#### Status word

4	3	2 *	1
1 = BitEtatLiss	1 = BitEtatChg	1 = BitEtat0	1 = BitMod0
2 = BitJbFill	2 = BitEtatPar	2 = BitEtat1	2 = BitMod1
4 = BitJbDelay	4 = BitJbWait	4 = BitEtat2	4 = BitMod2
8 = BitEtatCell **	8 = BitJbCar	8 = BitEtat3	8 = BitMod3

\*\*: only for sensor module (indicates presence of a sensor)

2 *	Status
0 ( EtatMes )	Normal measure
BitEtat0 ( EtatStab )	Stabilization
BitEtat1( EtatZInit )	Zero init
BitEtat0 + BitEtat1 ( EtatStab )	Zero Stabilization
BitEtat2 ( EtatZVal )	Zero validation
BitEtat0 + BitEtat2 ( EtatSWait )	Sensitivity waiting
BitEtat1 + BitEtat2 ( EtatSInit )	Sensitivity init
BitEtat0 + BitEtat1 + BitEtat3 ( EtatSStab)	Sensitivity stabilization
BitEtat3 ( EtatSVal )	Sensitivity validation
BitEtat0 + BitEtat3 ( EtatChg )	Button replace pushed

Мо	odule Designation	Туре
1	Sensor CO	0
2	sensorNO	1
3	Sensor NO <sub>2</sub>	2
4	Sensor EXPLO	3
5	Sensor O <sub>2</sub>	4
6	Free	5
7	Free	6
8	Other	7
9	4 relay mod	8
10	8 relay module	9
11	Free	А
12	Free	В
13	4ana output mod	С
14	16 log input mod	D
15	Analog input mod	Е
16	Free	F

#### **Bus Faults**

This menu displays the faults from all modules in a line. Each hexadecimal number corresponds to a module, with Module 1 being on the left, and Module 32 on the right.

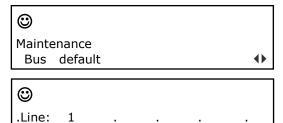
**0** = OK

1 = Communication error

2 = Module recognition error

4 = Fault triggered by a module fault word.

**X** = module missing or unrecognized due to a conflict with another module



Module 32

Module 1

Line: 1 Module: 1 = OK

Line: 1 Module: 2 = module recognition error Line: 1 Module: 3 = communication error

#### Reset maintenance

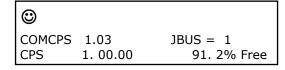
**1** Reserved for ISC- maintenance personnel only.



# CPS / COM\_CPS Version – Available memory level

Displays the CPS central controller version as well as the COM\_CPS programming software version.

Displays the microcontroller availability (time) rate (in %). This value will vary somewhat in relation to the program but can detect if a microprocessor is being overtaxed.



26 / 06 / 07

Enter the access code by using the  $[ ^{\blacktriangle} ] [ _{\blacktriangledown} ]$  and  $[ ^{\blacktriangleleft} ] [ ^{\blacktriangleright} ]$  keys.

Next, press the **[OK]** key to reinitialize all counters to zero and to refresh the date.

# 

0

acces

Installation CPS

#### **CPS Installation**

This menu is used to zero the following two settings across all modules: Last zero date

#### **Operating Time**

Each module logs its operation time in days. For the sensors, this time is equal to the time since the last calibration or the last zero.

#### Exceeding the scale

Each sensor logs the amount of time that levels exceed the scale in seconds. Go to the "Module Verification" menu to see this time.

## **Chapter 6** Maintenance

## **Program transfer**

This chapter describes the transfer of data from the COM\_CPS application to the CPS, and vice versa (see the COM\_CPS user's guide). After launching the software, you will see a welcome window.

#### **PC** → **CPS** transfer

Once the program has been created, the central controller should receive new settings...

#### Step 1: establish a physical connection

- Use either the USB or RS-232 adapter to connect the PC to the CPS central measuring controller.
- 2) Ensure that the CPS central measuring controller is connected to a power source.
- 3) On the central controller: flip the programming switch to the "MEM" position. The message "Switch open Program..." will appear on the display screen. Communication with the central controller is authorized during this phase..

#### Step 2: link configuration

- 1) In the menu bar, select [Communication > Port].
- Select the port [COM x] to use on the PC.

Note: communication speed is selected automatically

#### Step 3: data transfer

- In the menu bar, select [Transfer > from PC to CPS]. The message "Flip switch to MEM position in order to reprogram the central controller" refers to the <MEM> position on the CPS central controller commutator before starting the transfer procedClick [OK] once verification has ended.
- 2) During the transfer, a progress bar will indicate transfer progress.
- Once the transfer is complete, the message "Operation complete" will appear on screen. Click [OK]. The configuration program has been transferred from the PC to the CPS central controller.
- 4) On the central controller: The message "Switch open Complete" will appear on the display screen. Flip the programming switch to the "Prog" position.
- 5) The central controller will perform a "Start-up" procedure.

#### **CPS** → **PC** transfer

#### Step 1: establish a connection

- 1) Use either the USB or RS-232 adapter to connect the PC to the CPS central controller.
- Ensure that the CPS central measuring controller is connected to a power source.
- 4) On the central controller: flip the programming switch to the "MEM" position. The message "Switch open Program…" will appear on the display screen. Communication with the central controller is authorized during this phase.
  - Or, use the "Control" menu to set the printer to "OFF."

#### Step 2: link configuration

- In the menu bar, select [Communication > Port].
- Select the port [COM x] to use on the PC.

Note: communication speed is selected automatically.

#### Step 3: data transfer

- 1) In the menu bar, select [Transfer > from CPS to PC].
- 2) The message, "Do you want to read the CPS central controller configuration?" will appear onscreen. Click [OK]. If the message, "Check port configuration and ensure printer set to OFF position and try again" appears, verify that the CPS printer is in the OFF position.
- Select the folder where you want to download the file, and create a file name (a default name is suggested).
- 4) During the transfer, a progress bar will indicate transfer progress.
- 5) Once the transfer is complete, the message "Operation complete" will appear on screen. Click [OK]. The data has been transferred from the CPS central controller to the PC.
- 6) **On the central controller**: The message "Switch open Complete" will appear on the display screen. Flip the programming switch to the "Prog" position.
- 7) The central controller will perform a "Start-up" procedure.

## **Error messages**

Error messages will appear in the following scenarios:

ERR 01: Module fault relating to the program.

The test runs systematically on start-up and periodically when a module is activated by the menu if the module does not correspond to the loaded program. The error remains until the problem is corrected or until the module is shut down.

ERR 02: Fault word reading for a module. Name displayed on the 1st line of the screen.

ERR 04: Power line error.

ERR 08: I2C (real-time clock) or EEPROM error.

ERR 10: Module communication error.

ERR 20: Problem originating at printer. Printer shut-down or lack of paper.

#### **Checksum error**

When the central controller starts up, checksum values appear briefly on screen after the display test. The value calculated by the central controller is displayed on the first line, and the checksum calculated by the PC with the COM\_CPS software is displayed on the 2nd line.

If these two values are different, this screen will remain on the display screen, indicating that there is a problem (example: depleted battery.) The user program protection switch must be flipped, and a new COM\_CPS program must be transferred.

Flip the switch back into the "closed padlock" position before restarting the central controller.

# Operation before event CPS Analysis 21:04 Parking Charles de Gaulle

Technical alarm triggered (fault).
buzzer engaged (if activated),
Front panel yellow LED illuminated.
Two pictograms appear: the blinking
"maintenance key" and the "siren."

CPS Analysis
Parking Charles de Gaulle

Action on the front panel "acknowl" button.

Audible alarm (buzzer) is off.

"Siren" pictogram disappears.

"Maintenance key" pictogram remains on screen.

Front panel yellow LED illuminated.

CPS Analysis
Parking Charles de Gaulle

Action on the "acknowl" button.

Direct access to the "ERRORS" data page.

ERR 11 = ERR 10 + ERR 1

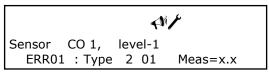
Communication fault for Module 1, Line 2.

<u>Communication fault</u> for Module 1, Line 2. Check the line and/or the module. The fault will disappear when the problem is resolved. Relay module level-1 ERR11 : Com. 2 01

21:04

If multiple errors occur, all of the error codes will be displayed one after another. The faulting modules for each error will be displayed one at a time by their line number and module number.

For all faults except for communication faults, the gas level will be displayed in order to help the user identify the problem.



## Testing and calibration of stable installations

Warning: The setting of this section are reserved for authorized persons formed because they might call into question the reliability of detection.

The site responsible is required to establish security procedures on its site. OLDHAM may be not responsible for their implementation.

Gas detectors are above all safety instruments. In consideration of this, **OLDHAM** recommends regular planned testing of fixed gas detection installations.

A functional test involves injecting a sufficient concentration of gas at the sensor level to trigger preset alarms. This test does not replace a full sensor calibration under any circumstances.

The frequency of gas tests depends on the industrial application in which the detector is in use. Frequent inspections should be made in the months following the commissioning of the installation, and then become more widely spaced provided that no significant deviation is observed.

If a detector should fail to react when in contact with the gas, calibration is essential. The frequency of calibrations is a function of the results of the tests (humidity, temperature, dust, etc.). However, it must not exceed one year. It is also advisable to calibrate the sensor after exposure to high concentrations of gas.

#### . Gas concentration which must be used during manual or semi automatic calibration

- CPS 10 CH4 = 2.5% CH4/air
- CPS 10 **H2** = 2% H2/air
- CPS 10 **C4H10** = 0.9% C4H10/air
- CPS 10 **CO** = 100ppm
- CPS 10 **NO** = 50ppm
- CPS 10 NO<sub>2</sub> = 10ppm

## Sensor replacement

Sensors should be replaced as a part of regular preventative maintenance or following a failed calibration test.

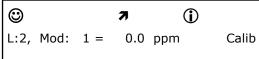
After replacing a sensor, a calibration test must be conducted (see the chapter on semi-automatic calibration).

To replace a sensor:

- Remove the sensor cover.
- Hold down the sensor replacement button (1) for 5 seconds, until the solid green LED (2) is on.
- Release the button.
- Replace the sensor and conduct a calibration test (mandatory) according to the semi-automatic procedure.

On the central controller, the "maintenance key" pictogram indicates that the sensor has been replaced. The key will remain on screen until the sensor has been calibrated or until the sensor's power supply fails. The wear settings for the sensor are initialized upon calibration

The wear settings for the sensor are initialized upon call



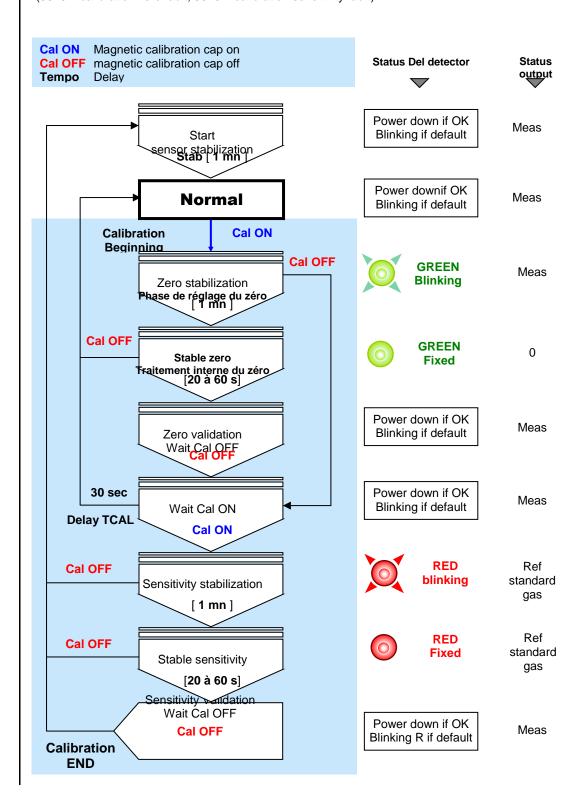
#### **Semi-automatic calibration**

During a sensor module calibration, the central controller blocks the alarms from the module in question and displays a maintenance key on the screen. Up to 10 sensors can be calibrated at the same time. The concentration level for the calibration gas is stored in the sensor's memory.

Each calibration start and stop is logged as an event.

The printer records a state after the calibration of each sensor (cf : Printing).

If the calibration is failed, the sensor is listed as faulting and an event is logged with a fault code (0010 - calibration zero fault, 0020 = calibration sensitivity fault).



#### **Manual calibration**

The calibration kit provided by ISC must be used (Ref. 6 116 291) female connector / wires / voltmeter connection files).

- Remove the sensor cover.
- Connect the cable (strand) to the circuit's male connector.

#### Zero adjustment

Ensure that the sensor is in clean air. If not, inject air into the sensor at a flow rate of 60 l/h, then wait for voltmeter levels to stabilize (use the gas injection device: bottle of synthetic air, calibration pipe, tube).

- Adjust the zero with the potentiometer's "ZERO" until the voltmeter reads 0 mV.

#### Sensitivity adjustments

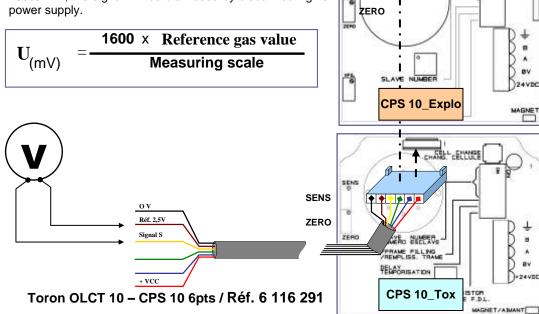
- Now inject the known gas (60 l/h) into the sensor, and wait for the voltmeter signal to stabilize.
- Adjust the sensitivity if necessary with the potentiometer "SENS" until the signal value (in mV) corresponds to the amount of reference gas used. Use the following formula to calculate the correct value for the signal.

SENS

- Stop injecting gas (remove the calibration pipe from the sensor).
- Wait for the voltmeter to "return to zero."

#### Version CPS 10 for explosive gas

The CPS central controller has a "**verification**" function: if the sensor measures a concentration of gas higher than 100% LEL, the signal will be dismissed by disconnecting its power supply.



#### **MAINTENANCE WIRES:**

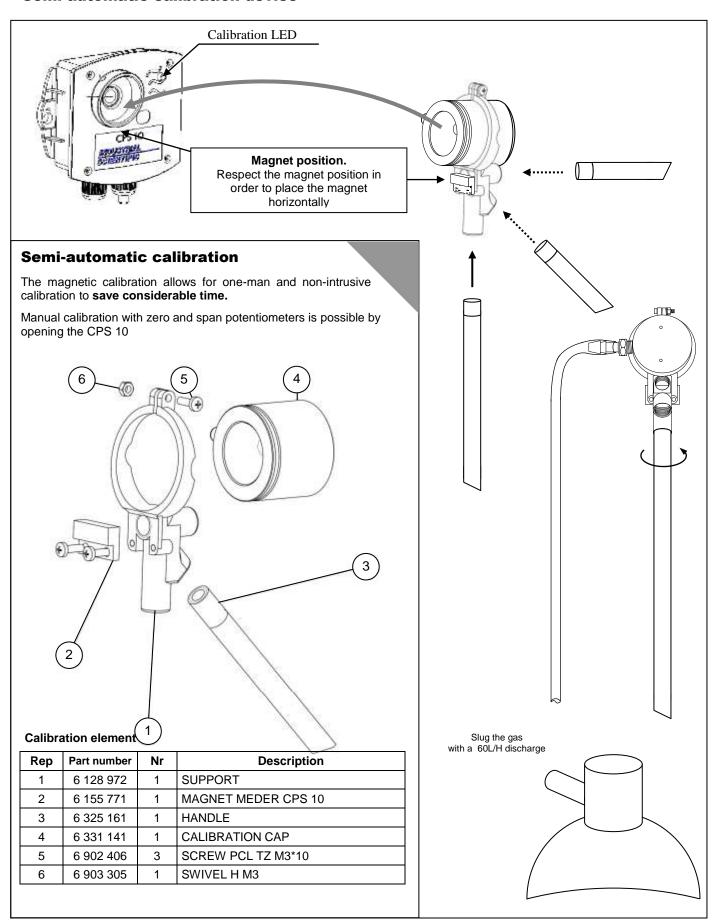
+VCC ( red ) = + power supply

**Signal S** ( yellow ) = signal from 0 mV to 1600 mV for zero and sensitivity measure Ref 2,5V ( brown) = zero reference for signal reading from 0 mV to 1600 mV

**GND** ( **black** ) = electronic circuit ground.



#### Semi-automatic calibration device



#### **Central controller maintenance**

Do not use alcohol- or ammonia-based liquids to clean the central controller. If necessary, clean the exterior of the central controller with a damp cloth.

#### Lithium battery

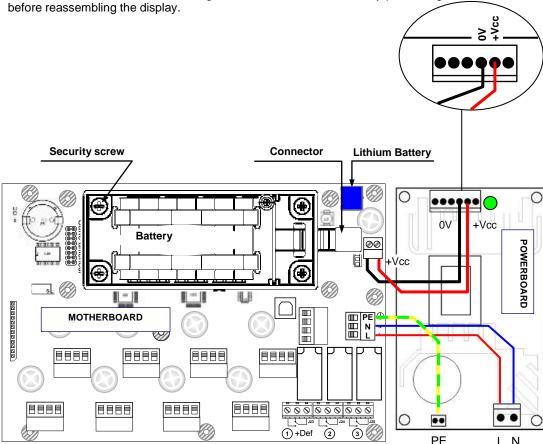
If the central controller configuration settings are lost, the lithium battery soldered to the display card must be replaced. This operation should be performed by a qualified professional.

Lithium battery characteristics: VARTA CR1/3N or equivalent.

#### **Back-up battery pack**

When the back-up battery power drops, the battery should be replaced. This operation should only be performed by a qualified professional.

The battery pack is located underneath the display screen on the wall-mounted version. Take off the display screen to access the battery pack. Unplug the connector linking the battery pack to the motherboard. Remove the 4 mounting screws. Attach the new battery pack. Plug in the connectors



## **Scrapping of CPS System**

Concerning the conservation, of the protection and the improvement of the quality of the environment, as well as for the protection of the health of the persons and the careful and rational use of natural resources, CPS system has to be the object of a selective collection for the electronic equipments and cannot be scrapped with the normal domestic waste. The user thus has the obligation to separate the CPS system of the other waste so as to guarantee that it is recycled in a sure way at the environmental level. For more details of the existing sites of collection, contact the local administration or the distributor of this product.



# **Chapter 7** Technical Specifications

CPS Central Contro	oller
CPS w/ metal wall-mounted casing:	Dimensions (mm): 320 x 180 x 95
	Degree of protection: IP 54
Cable entries	5 M20 cable glands Diameter 5-12 mm power / local relays 9 PG9 1 D-SUB 9 Pin RS-232 cable
CPS rack version	Dimensions: Length: 19" ; Height: 4 U (176 mm) IP class: IP 31
Operating conditions	
Ambient temperature:	-10°C to 40°C
Storage temperature:	-20°C to 85°C
Humidity:	5 to 95% noncondensing
Power supply	
Mains power supply:	Voltage: 110-240VCA
Battery back-up:	Optional – Capacity: 600 mAh
24 V Consumption:	140 mA + 12 mA per measurement line (240 mA max.)
Measuring lines	
Number:	8 RS-485 digital measuring lines
Line capacity:	32 digital CPS modules (CPS 10,CPS RM, CPS DI16, CPS AO4) ModBus Protocol
Cable type:	2 twisted pairs shielded RS-485 4Xawg22 (diameter 0.67mm) cable, 100 $\!$
Transmission speed:	9600 Bauds (trial with 0.35 mm²)
Module power supply:	12 to 30 VCC via the CPS central controller and if necessary via a 24VCC external additional power supply
Digital module network:	RS-485 ModBus, addresses 1 to 32, set with mini switches
Isolation:	Power supply / Digital network: 1500 V
Display	Backlit LCD display [ 2 lines, 32 characters per line - 1 line for pictograms - 3 electroluminescence diodes to indicate operating status: OK, Fault, Alarms ]
Keyboard	Membrane keyboard, 7 intuitive keys
Local buzzer	Alarm and fault signaling
Integrated printer	Optional for rack version (no integrated printer option for the metallic wall casing)
Alarms	
Number of alarms:	6 alarms per sensor (AL1, AL2, AL3, AL4, Out of Range, Fault + Validation for Explo gas)
Programmable thresholds:	For instantaneous or averaged values, increasing or decreasing values, or for manual or automatic rearming.
3 Internal local relays	Relay: R1 (alarm/fault) – R2 (alarm) – R3 (alarm).  Minimum charge for RCT contacts: 2A / 250 VAC – 30 Vcc (resistive charge)  Relays settings are configured with the COM_CPS configuration software.  Torque: 0.5-0.6 Nm
Centralized supervision system digital	
RS-485	ModBus Protocol (connection with a centralized supervision device)
RS-232 or USB	USB protocol priority (permanent connection to system configuration)
Approvals:	
Low Voltage Directive:	This device is in compliance with the security requirements of Directive 73/23/EEC, modified by Directive 93/68/EEC, based on standard 61010-1 and its second amendment.
Metrology:	Underground parking facilities: according to VDI 2053
EMC Electromagnetic compatibility:	according to EN 50270

CPS 10 Sensor N	/lodule
Dimensions (mm):	118 x 110 x 60
Degree of protection:	IP 65
Cable entries:	2 M16 cable glands 4-8 mm diameter
Consumption:	Toxic gas sensor: 2.5 mA in normal operation Explo gas sensor: 50 mA in normal operation
Status indication after calibration	Red/Green electroluminescent diode
Calibration:	Automatic, no need to open the sensor due to a gas introduction device equipped with a magnetic switch, or with a potentiometer inside of the case.
Sensor replacement:	Sensor replacement switch on the interior of the CPS 10 case.  Detection of sensor



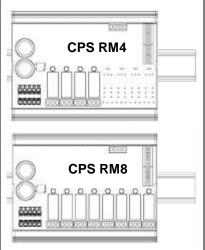
## **CPS RM4 or RM8 Relay Module**

Dimensions (mm):	125 x 165 x 60
Mounting:	Ratchets into DIN rail
Number of relays:	4 relays (CPS RM4); 8 relays (CPS RM8) Contact type: RCT
Minimum charge for contacts:	2 A / 250 V over resistive charge
Connection:	Screw posts (cable: 2.5 mm² max.) Torque : 0.5-0.6 Nm
Consumption:	3.5 mA in normal operation



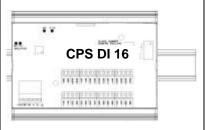
Configuration of positive or negative relay security with mini switches. Relay modules have 2 logic inputs.

Configuration via the COM\_CPS configuration software.



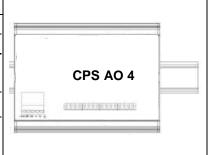
## **CPS DI16 Logic Inputs Module**

	-	
Dimensions (mm):	125 x 165 x 60	
Mounting:	Ratchets into DIN rail	
Number of All or Nothing Inputs:	16	
Connection:	Screw posts (cable: 1.5 mm² max.) Torque : 0.5-0.6 Nm	
Consumption:	2 mA in normal operation	



## **CPS A04 Analog Output Module**

Dimensions (mm):	125 x 165 x 60	
Mounting:	Ratchets into DIN rail	
Number of analog outputs:	4-20 mA output, max. resistance 500 $\Omega$ Isolation galvanique individuelle + 2 entrées logiques	
Connection:	Screw posts (cable: 1.5 mm² max.) Torque : 0.5-0.6 Nm	
Consumption under 24V at module input	I< 5 mA if the 4 channels are shut down I< 36 mA if only one channel is activated I<130 mA if all 4 channels are activated	



# **Chapter 8**

## **Annexes**

# JBUS/MODBUS Protocol

JBUS Transfer Table

Classification is automatically made by the COMCPS in the ascending order of the relays then modules then lines.

Nota: Relays and inputs are numbered, from 1 to 256 and from 1 to 64 in order to optimize the occupation memory in the CPS.

Acces in rea	d only by bit;	Acces in read only by bit; Function (1; 2)		Byte:							Byte	ø						Г
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1	0001	Alarm 1 Status of each detector module Module	2 bytes	M32	<u>8</u>	8	88	Z8 M	27 MS	86 M2	5 M24	123	Z	N2	8	8	2	17
2	0000		2 bytes	L. M6	7. E	7. M4.	7.EM	LI. M2 M	L1. L1. M11 M10	<u>=8</u>	=:≅	Ξξ	-:≅	F. 5	-:≅		11. M2. T1.	
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e	0003		2 bytes	M32	é	8	2 2 2 3		M27 M2	MZ8 MZ		_		M2	_		M 18	7
				12,	7		_			2	ŭ	ď	2	7	2	2	, [2	
4	0004		2 bytes	М16	M16	M14	M13 N		M11 M10					M6			M2 M	_
	-		2 bytes			П	H	Н	Н	Н	Н	Ц	Ц		Н	Н	Н	
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15	000F		2 bytes	S	_	8	8	28	28	Ю	24	ß	22	2	8	9	18 17	
				N'97	M	5	5	×	=	-	8,	89 ,	M.8.	5		8,ML	s,Mpr.b,M	Ę
16	0010		2 bytes	16	9	14	3	12 11	10	50	00	,	9	9	-	7	-	
				11,												_		-!
17	0011	Alarm 2 Status of each detector module	2 bytes	M32	MSI	88	RZW.	WZ8 W	MZ/ MZ6	8	D MZ4	SZ.	Z	MZI	32	8 10	LIN BLM	>
	=							+	$\dashv$	$\dashv$	$\perp$						-	
33	0021	Warm 3 Status of each defector module   Idem				П	H	Н	Н	Н	Н	Ц	Ц		Н	Н	Н	П
69	0031	Warm 4 Status of each detector module				Г	H	H	H	$\vdash$	H	L	L		Г	H	Н	
99	0041	Alarm overscale. Status of each detector module (dem				П	Н	Н	Н	Н	Н	Ц	Ц		Н	Н	Н	
91	1900	Warm fault Status of each detector module   Idem				Г	H	H	H	$\vdash$	L	L	L		r	H	H	
96	0900																	ı

					Z 18	918	9 18	p 18	£ 18	218	0 18	118	9 18	918	† <b>1</b> 8	E 18	Z 18	118	0 18
97	1900	Relays Status (delayed one	(puoces a		Ц														
76	1900	relays 1-8	9-16 Person	2 bytes	Relay 8	7/(glei	elay6	aysien				a fysia i	1elay16	१५ (र्रह्मान)	relay13	Shysien	r elay1 1	relay10	e(sle)
86	0062	relays 17-24	relays 25-32	2 bytes	relayat	relay23	ZZ/EB-I	rstayzı	oz/sei	elynsier	Siyalen Tiyalen			netay30	eSysien	sz/sen	<i>IZĮ</i> Elė I	egi/ge	rejsi/zę
66	0063	relays 33-40	relays 41-48	2 bytes	:								:	:					
100	0064	relays 49-56	relays 57-64	2 bytes									:	:					
101	9900	relays	relays	2 bytes									:	:					
112	0.000	relays 240-248	relays 249-256	2 bytes		• • •								• • •				• • •	• • •
113	1,700	= 187 # '±10 KBB 0 = 10 #	1 relay OV																

								7 118	9118	9 11E	P# 3	BILZ	1 118	0 1/8	9 118	9118	tr 1181	£ 149	2 118	1118	0.18
113	1,700	Module Fault																	H	l	
113	1,700	line fault		ine Bulti	тодие 2	Faut type for the both modules				enilgrithate Eur Er	TM, FLI Allm Ins TM, FLI	eluborninatni Lit , Mit	Module type L1,M1 Communicatio	u			enlignthete SM, tu ent milA	ZM, ra L1, M2 Intern module	Module type L1, M2	L1, M2 Communicatio	ц
114	2/00	line fault	ε епрош	me tautti		mebi	2 bytes	H	H	L	L	L	H	H	L		F	H	H	L	Г
115	8700		П	The Buff1	9 апрош	nebi	2 bytes	H	$\vdash$	H	L		H	$\vdash$	H		T	H	Н	H	
116	0074	line fault1		line fault1	module 8	Idem	2 bytes														
117	0075		module 9	line Bult1	module 10	Idem	2 bytes		H	Ц				H				H	Н	Н	
								Н	H	Н	Ц		Н	Н	Ц		d	Н	Н	Н	
128	0800	line fault1	1	line tault1	module 32	Idem	2 bytes	Н	H	Н	Ц		Н	Н	Ц		H	H	Н	Н	
129	0081	line fault2	module 1	line Bult2	module 2	idem	2 bytes	$\dagger$	$\dashv$	$\dashv$	$\coprod$		$\dagger$	$\dashv$	$\downarrow$			$\dashv$	$\dashv$	$\dashv$	П
	=		П					$\dagger$	+	4	4		$\dagger$	$\dashv$	4		1	$\forall$	┨	$\dashv$	П
145	1800	line fault3	module 1	ne auts	module 2	Idem	2 Dytes	$\dagger$	+	+	4	1	$\dagger$	+	$\downarrow$	1	<u> </u>	+	+	+	Т
181	0081	line fault4	module 1	The Buffd	module 2	Idem	2 bytes	$\dagger$	+	+	$\downarrow$		$\dagger$	+	$\downarrow$	$\perp$	T	+	+	+	Τ
		1	Т					t	+	╀	L	I	t	+	L		t	t	╁	╀	Т
111	00B1	line fault5	module 1	lne tault5	module 2	Idem	2 bytes	H	$\vdash$	$\vdash$	L		T	$\vdash$	L		T	H	H	H	П
			П					H	Н	Н	Ц		Н	Н	Ц	Д	H	Н	Н	Н	П
193	00C1	line faul6	module 1	lne tauft6	module 2	idem	2 bytes	H	H	Н	Ц		Н	H	Ц		Ħ	H	Н	Н	
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209	00D1	line faul?	module 1	ne aut7	module 2	Idem	2 Dytes	$\dagger$	+	+	4		$\dagger$	+	4	1		+	+	+	Т
338	0051	line fault8	modula 1	Pro faults	module 2	mejori	2 Profess	†	+	+	4	I	†	+	$\downarrow$	$\prod$	İ	$\dagger$	+	╀	Т
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240	0000	line fault8	module 31 The faut8	ne auts	module 32	Idem	2 bytes	t	+	╀	╀	I	t	╀	$\downarrow$	I	T	$\dagger$	╁	╀	Т
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241	00F1	forced operating.																			
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244	00F4	relay 49-56		relay 57-64			2 bytes	=				""				::	***				***
245	00F5	relay		relay			2 bytes					***	***			:	***				***
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EF 118	beeq8 fgH			l	EF 18		olds ft	16 bits de polds faible du long	4 bytes (32 bits not signed)	4 bytes (32 bits not signed)	32 bits not signed)	(32 bits not signed)	4 bytes (32 bits not stoned)		4 bytes (32 bits not stgred)	4 bytes (32 bits not signed)	4 bytes (32 bits not stated)		4 bytes (32 bits not signed)	4 hyles (32 bits not stoned)		4 bytes (32 bits not signed)	4 bytes (32 bits not signed)	١
141 118	Almentation			ı	141 118		de b	sdep	s (32	s (32	_	e (32	6 (32		s (32	s (32	6 (32	1	s (32	6 (35		s (32	8 (32	l
ar 118	- 1		Refer		ar 118		16 bit	16 bit	4 byte	4 byte	4 bytes	4 bytes	4 byte		4 byte	4 byte	4 byte		4 byte	4 hvfs		4 byte	4 byte	l
	Word	Word					2 bytes	2 bytes	2 bytes	2 bytes	2 bytes	2 bytes	2 bytes		2 bytes	2 bytes	2 bytes		2 bytes	2 bytes	1	2 bytes	2 bytes	
							4 bytes (32 bits not signed )																	
							Module 1		Module 2	Module 3	Module 4	Module 5	Module 1		Module 1	Module 1	Module 1		Module 1	Module 1		Module 1	Module 32	
	(NO)	g loon ON)					lne 1		line 1	The 1	line 1	Le i	lne 2		lne 3	lne 4	g eu		lne 6	7 edil	1	lne 8	Be 8	
	Fixed bors (if 1, fixed bon ON)	Birking toon (if1, blinking toon ON)				overscale delay	overscale delay		overscale delay	overscale delay	overscale delay	overscale delay	overscale delay		overscale delay	overscale delay	overscale delay		overscale delay	veleb delav		overscale delay	overscale delay	
	Floor	BII				ove	ove	Ц	ove	9//0	ev.o	ove	o/ve	Ц	ove	9//0	e//u		οve	G/VD	ò	ove	o/e	L
	0116	0117	2			7531	7531	7532	7633	7535	7637	7539	7571		7581	75F1	7631		7671	7681		78F1	772F	7730
	278	279	vinobecraecoA			30001	30001	30002	30003	30008	30007	30008	30065		30129	30193	30057		30321	30386		30449	30511	61308

						21 18 21 18 21 18 21 18 21 18	7 18 8 18 8 18 8 18 2 18 1 18
30613	7731	Timer since latest calibration					
20013	1731	Sest calibration		Module 1	Word	2 Dytes (16 Dits not signed)	
41000	7132	latest calibration		medule 2	DEAL	z úytes ( 16 tils Roll signed)	
30015	//33	atest calibration	-	wodne 3	WORD	2 bytes (16 bits not signed)	
30516	7734	atest calibration	Le l	Module 4	Word	2 bytes (16 bits not signed)	
30617	7735	atest calibration	Tre 1	Module 5	Word	2 bytes (16 bits not signed)	
30540	774C	latest calibration	lne 1	Module 28	Word	2 bytes (16 bits not signed)	
30641	774D	latest calibration	lne 1	Module 29	Word	2 bytes (16 bits not signed)	
30542	774E	latest calibration	lne i	Module 30	DIOW.	2 bytes (18 bits not signed)	
30643	47.7F	latest calibration	Lea 1	Module 31	Word	2 bytes (16 bits not signed)	
30644	7750	latest calibration	Te 1	Module 32	Word	4	
30645	7751	latest calibration	lhe 2	Module 1	Word	2 bytes (16 bits not staned)	
SORAR	7752	stest calibration	C et al	Wording 2	Word	2 hytes (18 hits not stoned)	
04000	2011		*		The same	z proces ( to bits lost segreta)	
30677	7774	latest relibration	5 94	Develop 4	Month	2 halos (18 hite not elemant)	
7,000		CACCOL CONTROL OF THE	2	- Survey	TA CA	A PRICE   TO DIE HOLD SHOW!	
30900	7704	dest relibration	y ou	Chodula 1	Laury (A)	2 halos (18 hits not signad)	
00000			+	- Carrier	201	(notification of the soliday)	
306.44	7704	odiate collassimo	Pro 6	Parents 1	Mond	2 hidas (18 hite not alonad)	
1000			2		200		
20023	77.04	locate collamination	8 04	Modulo 4	Mond	2 hidae ( 18 hite pot elemad)	
2 2000	10.0	laces cancional			TA CALL	z výtes ( 10 ble lot signal)	
30705	7751	latest calibration	Lue 7	Module 1	Word	2 bytes (16 bits not staned)	
						1	
30737	7811	latest calibration	line 8	Module 1	Word	2 bytes (16 bits not signed)	
30768	7830	latest calibration	lhe 8	Module 32	Word	2 bytes (16 bits not signed)	
30769	7831						
						1	
						1 15 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	71 81 81 81 81 11
00000	7007	der of of mouse board on so more	to di modifici f	000	(Alexander		8 8 8
Samo	100		non ( Illonno	(000	IVCAU	z nytes ( to trib int signed)	
30770	7832	4-1 if the system chesnit received	eceive its 1200 events		Word	2 hyles (16 bits not stoned)	
30771	7833	event to be pri			Word	2 bytes (16 bits not staned)	
						1 2 1 1 2 2	1 2 1 1 9
30772	7834	EMPTY				118 118 118 118 118 118 118	118 118 118 118 118
30809	1869	event					
30809	1859	event N				Day	Month
30810	785A	event N				Year	Hour
30811	785B	event N				Minute	seconde
30812	785C	event N				Module number	event number
30813	785D	event N				Extra Information	Extra Information
30814	785E	event N+1				Day	Month
30815	785F	event N+1					Heure
30816	7860	event N+1					seconde
30817	7861	event N+1					Event number
30618	7862	event N+1				Extra incrmation	Extra information
	200	COV 27 22 \$200000				Bank to more har	Newspeed
36909	0FC/8	Well N+1189				Module number	No everil
00000	2010	COLUMN TO SERVICE SERV		The section of	1000	Extra ilitatilation	EALGINGHIGH
20010	5010	on the RSI pillier		(Madula 4)	WCAG		
36904	orcs onto	Tool Mar 4 80 hide tool					
36074	9000	Tool Man 2 80 bide tool					
37051	anda	80 hyla					
-	2200	or or or			$\Big]$		

					-	3yle1 Byle2
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	9					21 III 21
10000	JBUS	Delegate model rose			T	
40001	9C41	Instantaneous messure	i eri	Module 1 1 V	Word	2 Mes (18 bits not streed)
40002	9C42	Ī	Te 1	2	Γ	
40003	9C43	T	Te 1		Γ	2 bytes (16 bits not signed)
40004	9C44	f	Te 1	Wodule 4	Γ	2 bytes (16 bits not staned)
40005	9C45	T	Te 1		Г	2 bytes (16 bits not storned)
		1			T	
40028	9050	Instantaneous measure	ne 1	Module 28	Word	2 bytes (16 bits not slaned)
40029	9050	Ť	Le 1		Т	
40030	9CSE		Te 1		Т	41-
40031	9CSF		Te 1		Т	bytes (
40032	9C60	T	T er		Т	2 bytes (16 bits not stoned)
40033	9061	T	ne 2		Т	2 bytes (16 bits not signed)
40034	9062	T	The 2		Γ	
		١			Γ	
40065	9C81	Instantaneous measure	ne 3	Module 1	Word	2 bytes (16 bits not signed)
					П	
40097	9CA1	Instantaneous measure	lne 4	Module 1	Word	2 bytes (16 bits not signed)
00000		ľ			T	A broken of all the conductions of
40129	LOOR	Installaneous measure	0 00	Module 1	WOR	2 Dytes (16 DIS not signed)
40161	9CE1	Instantaneous measure	De 6	Wodue 1	Word	2 bytes (16 bits not stared)
		1			T	
40193	9001	Instantaneous measure	lne 7	Wodule 1	Word	2 bytes (16 bits not signed)
		ľ			7	
40225	9D21	Instantaneous measure	Le 0	Module 1	Word	2 bytes (16 bits not signed)
40256	9D40	Instantaneous measure	ne 8	Module 32	Word	2 bytes (16 bits not signed)
Ī	FPU6	1			1	
40004	1	-				
					_	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
						8tt
40257	9D41	4-20mA Outputs Value ( 1000 = 1	1mA)			
40257	9D41		output		7	2 bytes (16 bits not signed)
40258	9D42	value	Outputs		7	pytes (
40209	9D43		oulpurs		T	2 pytes (16 pits not signed)
40260	9044	Output4-20mA Value o	output4		Word	
4,0000	8049		outhrip		Ť	
40002	9040		outputs		T	Z Dytes (16 Dits Filt Signed)
40003	904/	Output4-20m4 Value	output		T	Z Dytes (16 Dits FRI signed) 3 hidse (18 hits not storned)
40204	0000	ľ	outra do		T	Spiros (19 bits not element)
90000	8048	ľ	cultura		T	Z Výtes (10 Vís Nú Byland) S Judeo (10 byla pod storoval)
40087	arus	Output-20m8 Value	outrath1		Word	2 pytos (10 bila military art)
40068	DPU6	Ī	outst42		T	-1-
00000+	2500	1	za invitro		T	(name interest and a series
40612	9E40	Output4-20mA Value o	output256		Word	2 bytes (16 bits not staned)
40613	9E41				1	

21.10 11.10	(petr)	(ped)	(pad)	(grad)		(ged)		(gred)	(Ded)	(ped)	(pad)	(pad)	(Decd)		(dad)	2 5 9 9	18 18 18 18 18	(Ded)	(Ded)	(gred)	(died)		(Dead)	ged	(pedit)	(ped)	(gred)	patri		lgred)	(Ded)	(gred)	(Ded)		(pad)	(Ded)
81 18	Word 12 bytes (16 bits not stoned	2 bytes (	Word 2 bytes (16 bits not signed	Word 2 bytes (16 bits not signed)	П	Word 2 bytes (16 bits not signed) Word 2 bytes (16 bits not signed)	П	Word 2 bytes (16 bits not signed)	Word 2 bytes (16 bits not signed)	Word 2 bytes (18 bits not signed)	Word 2 bytes (16 bits not signed)	Word 2 bytes (16 bits not signed	Word 2 bytes (16 bits not signed)	П	Word 2 bytes (16 bits not signed)	51 51	18	Word 2 bytes (16 bits not stoned)	Т	Word 2 bytes (16 bits not signed)	Т	П	Word 2 bytes (16 bits not signed)	Τ		П	Word 2 bytes (16 bits not signed) Word 2 bytes (16 bits not signed)	More ( 18 biles of 18 biles and signed	Т	Word 2 bytes (16 bits not signed)	Word 2 bytes (16 bits not signed)	Word 2 bytes (16 bits not signed)	Word 2 bytes (16 bits not signed	П	Word 2 bytes (16 bits not signed)	Word 2 bytes (18 bits not signed)
	I Poduje 1	Module 1	Module 1	Module 1		Module 1 Module 1		Module 1                           Module 1		Module 32			I I I I I I I I I I I I I I I I I I I	Module 2	Module 3	Wodule 5		Module 26	Module 30	Module 31	Module 32	Module 1	1 direction 1		Module 1	Module 1	Module 1	Module 1		Module 1	Module 32					
	Detector measures  Viveraged measure 1   The 1	2	Averaged measure 3 line 1			Averaged measure 1 line 2 Averaged measure 2 line 2		Averaged measure 1 line 3	Averaged measure 1 Ine 4	Averaged measure 1 line 5	Averaged measure 1 line 6	Averaged measure 1	Averaged measure 1 line 8		Averaged measure 1 line 8			Maximum measures   The 1			Maximum measure line 1		Maximum measure The 1	T			Maximum measure Ine 2	S erill enissem minnback		Maximum measure The 4	Maximum measure line 5	Maximum measure   The 6	Maximum measure		Maximum measure The 8	Maximum measure Ine 8
JBUS	40613 9E41 C	9E42	9E43	40517 9E45 7	=	40641 9EC1 A	***	40769 9F41 A	40897 9FC1 A	4 1025 A041 A	41153 AOC1 A	41281 M141 A	4 1409 A1C1		A240	4 ISST PASS		41537 A241	3 A242	41539 A243 h	A245	111	41564 M25C	AZSE	A25F	A260	41570 A262 N	1 1804 10818		41633 A2A1 N	41885 A2C1 N	41697 A2E1 N	41729 A301 N	=	41761 A321 N	41792 A340 N

	9		21 th	01
	Snac			4
41793	A341	Detector measures		
41793	A341	Sentences		
41794	A342	Sentencer		
41795	A343	Sentencer		1
41796	A344	Sentence1		
41797	A345	Sentencet	Byte9 Byte10	
41797	A345	Sentencer	Byte11 Byte12	
41798	A346	Sentencet	Byte13 Byte14	
41799	A347	Sentence		Γ
41800	A348	Sentence		Γ
41801	A349	900000		Γ
41804	0.540	Santagoo		T
000077	2000			T
4.1802	ASKA	Centercel		1
41803	A34B	Sentence1		
41804	A34C	Senterce1	Byte27 Byte28	
41805	D1SAD	Sentence1		Γ
41806	A34E	Sentence		Γ
41807	ASAE	S. Della Co.	econstruct the end of the sentence	Γ
4 4808	0.50 0		1	1
4 1000	nacu			ſ
			2 9 9 6 6 10 10 10 10 10 10 10 10 10 10 10 10 10	
	JBUS		118 118 118 118 118 118 118 118	HE
4 1808	4350	Detaclor measures		ı
4808	036.0	Soniores	Dates	Ī
44000	A 25.4	ZONIENDO		
6001.6	ASOT	Sellielisez		
41810	A352	Sentence2		1
41811	A353	Senterce2	Byte7 Byte8	
41812	A354	Sentence2	Byte9 Byte10	
41812	A354	Senieroe2	Byle11 Byle12	Γ
4.1813	ASSE	Santarres		
41814	A 356	Santana2		Ī
41815	A 35.7	Santanas Santanas		Ī
41816	A 35.R	Sentiannes		T
4 1818	A 35.8	Santagoo		T
44047	O JC V	Control		Ī
1101.6	9000	Zerlinites		T
4 1818	ASSA	Sellierosz		
41819	A35B	Sentence2		
41820	A35C	Senterce2	Byte29 Byte30	
41821	A35D	Sentence2	Byte31	
41822	A36E	Sentemos2	Byte33 / ferm at the end of the sentence Byte34 / empty	Г
41823	A35F		1	1
			2 5 9 9 6 0 1 1 1 2 1 2 1 2 1 1 1 1 1 1 1 1 1 1 1	L
			118 118 118 118 118 118 118 118 118 118	118
41823	A36F	Remoted keyboard Word		
41824	A380			Γ
44055	A GOT			1
4 100D	ASIT			

SETTINGS VIA COMCPS	ACOMCPS		Byte1	Byte2
			ᆫ	3 9
	JBUS		1181 1181 1181	118 119 119 119 119 119 119 119 119
50001	1983	Module list		
50001	C351	Module 1 Name (32byte)	Byte 1 Name	Byte 2 Name
50017	C361	Module type (1 byte) Relay position (1 byte)	Module type (1 byte)	Indice relay (1 byte)
50018	2983		(6	Config by fault (1 byte)
50019	සෙ	Module 2 Name (32byte)	Byte 1 name	Byte 2 name
	0000	The state of the s		
50035	C373	Module type (1 byte) relay position (1 byte)	Module type (1 byte)	Relay position (1 byte)
50036	C374	Input Position (1 byte) Config by fault (1 byte)	Input position ( 1 byte )	config by fault (1 byte)
	0000			
54591	389C	Module name 256 (32byte)	Byte 1 name	Byte 2 name
	0000			
54607	D54F	Module type (1 byte) Relay position (1 byte)		Relay position (1 byte)
54608	DE50	Input position (1 byte) Config by fault (1 byte)	Input position (1 byte)	Config by fault (1 byte)
54609	D651			
			6: 01: 11: 21: 71: 91:	0 : 2 : 3 : 3 : 3 : 3 : 3 : 3 : 3 : 3 : 3
	JBUS		18 18	18 18 18
54609	1990	Relay list		
0.4000	1334	and the second section of the second sections are second to second secon	Care Of resistance students	Relay number on the
54810	0663	contract (10)	Dylot name	Date 2 name
	2000			
54620	D66C	HS position / function output4-20mA (1byte) empty Byte 2 bytes	HS position	
54621	0990	Module number (1byte) and Relay function and position (1b)	Module number (0-255)	Relay function number Relay number on the
54622	D66E	Relay Name Joulput 2 (20byte) 2 bytes	Byte 1 name	Byte 2 name
			┪	
54632	D568	HS Position / function output4-20mA (1byte) empty Byte 2 bytes	HS Position	
67669	E145	(1position and function (1b)	Module number (0-255)	Relay function number Relay number on the
		Relay Name Jourpul256 (20byte) 2 bytes	Byte 1 name	Byte 2 name
			П	
		HS position / function output4-20mA (1byte) Empty Byte 2 bytes	HS position	
57681	E161			

	5			21 11 21 11 21 11 11 11 11 11 2 1	41 41 511 511 511 611
57681	JBUS E161	Urbut list		88 88 88 88 88 88 88 88 88 88 88 88 88	8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8
57681	E151	Module number (1 byte) and input number (1b)	2 bytes	Module number (0-255)	Relay function number Relay number on the
57682	E152			Byte1 Name	Byte 2 Name
57692	E15C	Module number (1byte) and relay function and position (1b)	on (1b) 2 bytes	Module number (0-255)	Relay function number Relay number on the
57693	E15D	Input 2 name (20byle)	2 bytes	Byte1 Name	Byte 2 Name
60431	ECOF	<ul><li>and input number (1b)</li></ul>		Byte1 Name	Bytez Name
		Input 1 name (20 byle) rek	relay position (1 byte) 2 bytes	Module type (1 byte)	Relay position (1 byte)
60442	EC1A	_			
		DETAILS AND DADAMETEDS OF THE 10 TYPES	VEST OF BYSHIP I SENSODS ABSTRACTOR	(50)	
		DELONGO POPULIE EN OF THE 10 TIPES	or resident streets (Negery Foods)	(2.5)	
				0 Z 7	
	BUS			1 118 1 118 1 118 1 118 1 118	311 5 311 6 311 6 311 7 311 7 311 7 311 7 311 7
60462	ECZE	List units of the modules			
60462	ECZE	gaz name for type 1 (6 bytes)		Byte1 Name	Byte2 Name
60465	EC31	gaz name for type 2 (6 bytes)		Byte1 Name	Byte2 Name
000	0	The state of the state of the state of			
60489	EC49	gaz name tor type 10 (s bytes)		Byte1 Name	Bytez Name
00000	0801				
28400	240	_			
				11 11 12 13	8
	JBUS			. 18 . 18 . 18 . 18	18 18 18 18 18 18 18
60492	EC4C	Code of detector gas type			
60492	EC4C	Gas code for type 1 and 2 (2 bytes)		Code type 1	Code Type 2
60493		Gas code for type 3 and 4 (2 bytes)		Code type 3	Code Type 4
00700		The second for the second of the second		5	20 mm
60496		cas code for type 9 and 10 (2 bytes)		coe type 9	code Type 10
60497	ECS1	_			
				0 Z	
	BUS			18 118 118 118 118 118	18 1 18 1 18 1 18 1 18 1 18 1 18 1 18
60497	EC51	Instantaneous alarm threshold			
60497	EO51		ype 1 Word	_	
60498	EC52			2 bytes (16 bits not signed)	
60439	EC53	hstantaneous alarm 1 threshold Ty	Pype 3 Word	2 bytes (16 bits not signed)	
90909	ECSA			2 bytes (16 bits not signed)	
60607	ECSB			2 bytes (16 bits not signed)	
60909	2020	Installaneous agrill 2 threshold TV	Type 2 Word	2 bytes (16 bits not signed)	
60616	EO84	hstantaneous alarm 2 threshold Ty	Type 10 Word	2 bytes (16 bits not signed)	
00000	00001		Table 1997	Charles of the bull of the control of	
ocono	EUO	INTRINGUES ARTIN 4 UNESTON	Type 10	Z Dytes ( 10 Dits Not Signed)	

21 118 6 118 6 118 6 118 6 118 7 118 8 119 8 119 8 119 8 119 8 119 8 119 8 119		Type 1 Word (2 bytes (16 bits not signed)	Type 2 Word (2 bytes (16 bits not signed)	Word 2 bytes (		Type 10 Word 2 bytes (16 bits not signed)	Type 1 Word (2 bytes (16 bits not signed)	Word	Type 3 Word (2 bytes (16 bits not signed)		Type 10 Word (2 bytes (16 bits not signed)	Type 10 World 2 bytes (16 bits not signed)	2 2 8 9 6 0 L L L L L L L L L L L L L L L L L L	118 118 118 118 118 118 118 118 118 118		Type 1 Word (2 bytes (16 bits not signed)	Type 2 Word 2 bytes (16 bits not signed)	Type 3 Word (2 bytes (16 bits not signed)		Type 10 World 2 bytes (16 bits not signed)	2 2 7 9 9	18 18 18 18 18 18		2 bytes ( )	Type 2 Word (2 bytes (16 bits not signed)	Type 3 Word (2 bytes (16 bits not signed)	 There 40 Milesel 10 holes ( 4.0 hile post element)
	p	Δ.	1	1	:	F	-	1	1	-	1	_				Type 1	Type 2	Type 3		Type 10			P	Type 1	Type 2	Type 3	 Trees 40
	Averaged alarm threshold	Averaged alarm 1 threshold	Averaged alarm 1 threshold	Averaged alarm 1 threshold		Averaged alarm 1 threshold	Averaged alarm 2 threshold	Averaged alarm 2 threshold	Averaged alarm 2 threshold		Averaged alarm 2 threshold	Averaged alarm 4 threshold			Fault Alarm Threshold	Aarm threshold	Alarm threshold	Alarm threshold	::	Alarm threshold			Overscale Alarm threshold	alarm value	alarm value	alarm value	 
JBUS	EC79	EC79	EC7A	EC7B		EC82	EC83	EC84	EC85		ECSC	ECA0		JBUS	ECA1	ECA1	ECA2	ECA3		ECAA		JBUS	ECAB	ECAB	ECAC	ECAD	
	60637	60637	60638	60936		80546	60547	60648	60649		99909	80678			22909	60677	80678	62909		60586			60687	60587	88909	68909	

	JBUS			27 118 27 118 27 118 77 118 9 118 9 118 2 118 2 118 2 118
78000	ECBB	Averaged stairm detay	Sec. 1	2 halos (48 his roll circus)
80698	ECBS	averaged alarm 1 Delay		Τ
66909	ECB7	averaged alarm 1 Delay		Т
				П
90909	ECBE			7
80607	ECBF	averaged alarm 2 Delay	Type 1 Word	2 bytes (16 bits not signed) 2 bytes (18 bits not signed)
60909	ECCI			2 bytes (
				П
90919	ECC3	averaged alarm 2 Delay	Type 10 Word	2 bytes (16 bits not signed)
90939	ECDC	averaged alarm 4 Delay	Type 10 Word	2 bytes (16 bils not signed)
				1
	2			21 110 110 110 110 110 110 110 110 110 1
80837	ECDD	Hysteresis Value		
60637	ECDD	Hysterests	Type 1 Word	2 bytes (16 bits not signed)
60638	ECDE	Hysteresis	2	П
60936	ECDF	Hysteresis	Type 3 Word	2 bytes (16 bits not signed)
RDRAR	ECER	Helmele	 Does 10	2 hydes (18 his polisimed)
05000	EVED			٦
				2 2 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3
	JBUS			8 11 1 8 1 1 8
60647	ECE7	RESERVE COMOPS		
80648	ECES		Type 1 Word	2 tytes (16 tyte not stoned)
60649	ECE9			П
	6			П
99099	ECF0		Type 10 Word	2 bytes (16 bits not signed)
	Snar			21 1188 21 1188 21 1188 21 1188 21 1188 21 1188 21 1188 21 1188 21 1188 21 1188 21 1188 21 1188 21 1188 21 1188 21 1188 21 1188
60657	ECF1	Enable or disable Alarms		
60657	EGET	Tone 1/1 bytes	Tune 2/1 bytes	M4 aver 101 M2 aver 101 M3 aver 101 M4 may 101 M4 may 0n
80858	ECF2			TO Tens 8/4 TO Ten
				S INSTON T I
60661	ECF6		Type 10 (1 byte) 2 bytes	114 114 115 116 117 117 118 118 118 118 118 118 118 118
		# bit= 1 enable alarm		

Case name for type 2 (1 bytes)   Type 3 (1 bytes)   Type 4 (1 bytes)   Type 6 (1 bytes)   Type 7 (1 bytes)   Type 6 (1 bytes)   Type 7 (1 bytes)		SIBOS			21 118 21 118 21 118 11 118 01 118 8 118	2 H8 2 H8 2 H8 2 H8 2 H8 2 H8
ECT   Type 3(1 byte)   Type 2(1 byte)   Type 2(1 byte)   Type 1   Type 2    60662	ECF6	Checking of the type of corrected detector				
ECTA   Type b(1 byte)   Type 10 (1 byte)   2 bytes   Code detects type 9   ECTA   Type b(1 byte)   Type 10 (1 byte)   2 bytes   Code detects type 9   ECTA   Type b(1 byte)   Type 10 (1 byte)   2 bytes   Code detects type 9   ECTB	60662	ECF6			1	Code detector type 2
1980   1980	60663	ECF7			Code detector type 3	Code detector type 4
ECCE   Case name for type 1 (5 bytes)   ECCE   Case name for type 2 (5 bytes)   ECCE   Case name for type 2 (5 bytes)   Traine 2 Byte 4   ECCE   Case name for type 2 (5 bytes)   Traine 2 Byte 4   ECCE   Case name for type 2 (5 bytes)   Traine 2 Byte 4   ECCE   Case name for type 2 (5 bytes)   Traine 2 Byte 4   ECCE   Case name for type 2 (5 bytes)   Traine 2 Byte 4   ECCE   Case name for type 1 (15 bytes)   Traine 2 Byte 4   ECCE   Case name for type 1 (15 bytes)   Traine 2 Byte 4   ECCE   EC	99909	ECFA	De 9 (1 byte)	ŀ	Code detector type 9	Code detector type 10
ECPE   Cass name   Cass name						
ECFE   Gas name for type 1 (5 bytes)   ECFE   Gas name for type 1 (5 bytes)   ECFE   Gas name for type 1 (5 bytes)   Institute 2 (5 bytes)   Institute 3 (5 bytes)   Institu					2 2 3	
ECFB         Gas rame for type 1 (5 bytes)         Name 1 Byte 1           ECFD         Gas rame for type 2 (5 bytes)         Name 1 Byte 2           ECFF         Gas rame for type 2 (5 bytes)         Name 2 Byte 4           ECFF         Gas rame for type 2 (5 bytes)         Name 2 Byte 4           ECFF         Gas rame for type 2 (5 bytes)         Name 2 Byte 4           ECFF         Gas rame for type 1 (5 bytes)         Rame 2 Byte 4           ED13         Gas rame for type 1 (16 bytes)         Rame 10 Byte 1           ED14         Gas rame for type 2 (16 bytes)         Name 2 Byte 1           ED15         Gas rame for type 2 (16 bytes)         Name 2 Byte 1           ED16         Gas rame for type 2 (16 bytes)         Name 2 Byte 1           ED18         Gas rame for type 10 (16 bytes)         Name 2 Byte 1           ED63         Gas rame for type 10 (16 bytes)         Name 2 Byte 16           ED64         Type 1(1 byte)         Type 2(1 byte)         Z bytes         Display format code type 3           ED64         Type 9(1 byte)         Type 4(1 byte)         Type 1(1 byte)         Z bytes         Display format code type 3           ED68         Type 9(1 byte)         Type 1(1 byte)         Type 1(1 byte)         Z bytes         Display format code type 3		SING			r 116	3 11 6 3 11 6 3 11 4 3 11 5 3 11 5 3 11 5
ECFB         Case name for type 1 (5 bytes)         Norm 1 Byte 5           ECFF         Case name for type 2 (5 bytes)         Iname 2 Byte 2           ECFF         Case name for type 2 (5 bytes)         Iname 2 Byte 4           ECFF         Case name for type 2 (5 bytes)         Iname 2 Byte 4           ECFF         Case name for type 1 (5 bytes)         Iname 2 Byte 4           ED13         Case name for type 2 (5 bytes)         Iname 2 Byte 4           ED14         Case service of mane         Iname 2 Byte 4           ED14         Case name for type 1 (16 bytes)         Iname 2 Byte 1           ED15         Case name for type 2 (16 bytes)         Iname 2 Byte 1           ED18         Case name for type 1 (16 bytes)         Iname 2 Byte 1           ED19         Case name for type 1 (16 bytes)         Iname 2 Byte 1           ED6         Type 1 (1 byte)         Type 2 (1 byte)         Iname 2 Byte 15           ED6         Type 3 (1 byte)         Type 2 (1 byte)         Iname 2 Byte 15           ED6         Type 9 (1 byte)         Type 9 (1 byte)         Iname 2 Byte 15           ED6         Type 9 (1 byte)         Type 9 (1 byte)         Iname 2 Byte 15	19909	ECFB	Gas name			
ECFE         Gas rame for type 2 (5 bytes)         Name 2 Byte 2           ECFE         Gas rame for type 2 (5 bytes)         Iname 2 Byte 4           ECFE         Gas rame for type 2 (5 bytes)         Iname 2 Byte 4           ED13         Gas rame for type 10 (5 bytes)         Iname 10 Byte 4           ED14         Gas rame for type 10 (5 bytes)         Iname 10 Byte 4           ED14         Gas rame for type 1 (16 bytes)         Iname 1 Byte 1           ED14         Gas rame for type 1 (16 bytes)         Iname 1 Byte 1           ED13         Gas rame for type 2 (16 bytes)         Iname 2 Byte 1           ED63         Gas rame for type 1 (16 bytes)         Iname 2 Byte 15           ED64         Display formal code type 1         Inpe 2 (1 byte)         Inpe 2 (1 byte)         Inpe 3 (1 byte)           ED64         Type 3 (1 byte)         Type 4 (1 byte)         2 bytes 1 byte 3 (1 byte)         Inpe 3 (1 byte)         Inpe 3 (1 byte)         Inpe 3 (1 byte)           ED68         Type 9 (1 byte)         Type 10 (1 byte)         Inpe 3 (1 byte)         Inpe 9 (1 byte)         Inpe 9 (1 byte)         Inpe 9 (1 byte)	19909	ECFB	Gas name for type 1 (5 bytes)			Nom 1 Byte 2
ECFE   Case name for type 2 (5 bytes)   Name 2 bytes 2   Pate 2   Pate 3     ECFE   Case name for type 2 (5 bytes)   Name 2 bytes 4     ECFE   Case name for type 2 (5 bytes)   Name 2 byte 4     ECFE   Case name for type 1 (5 bytes)   Name 2 byte 4     ED14   Case name for type 1 (16 bytes)   Name 1 byte 1     ED15   Case name for type 1 (16 bytes)   Name 2 byte 1     ED16   Case name for type 1 (16 bytes)   Name 1 byte 1     ED17   Case name for type 1 (16 bytes)   Name 2 byte 1     ED18   Case name for type 1 (16 bytes)   Name 2 byte 1     ED19   Case name for type 1 (16 bytes)   Name 2 byte 1     ED19   Case name for type 1 (16 bytes)   Name 1 byte 1     ED19   Case name for type 1 (16 bytes)   Name 1 byte 1     ED19   Case name for type 1 (16 bytes)   Name 2 byte 2     ED19   Case name for type 2 (16 bytes)   Name 2 byte 3     ED19   Case name for t						
ECFE   Gass name for type 2 (5 bytes)   Frame 2 Byte 2   Frame 2 Byte 4   Frame 3 Byte 4   Frame 4 Byte 4	69909	ECFD	Gas name for type 1 and 2 (5 bytes)		Norm 1 Byte 5	name 2 Byte 1
ECFF   Cass name for type 2 (5 bytes)   Iname 2 Byte 4	0.000	ECFE	Gas name for type 2 (5 bytes)		name 2 Byte 2	name 2 Byte 3
ED13   Casa rame for type 10 i5 bytes)   Paris   Par	60671	ECFF	Gas name for type 2 (5 bytes)		name 2 Byte 4	name 2 Byte 5
ED13   Casa name for type 10 (5 bytes)   Paris 10 bytes 4   Paris 10 bytes 4   Paris 10 bytes 4   Paris 10 bytes 4   Paris 10 bytes 5   Paris 10 bytes 6   Paris 10 bytes 7   Paris 10						
ED14   Cass shortened name   ED14   Cass rame for type 1 (16 bytes)   ED14   Cass rame for type 2 (16 bytes)   ED14   Cass rame for type 1 (16 bytes)   ED18   Cass rame for type 1 (16 bytes)   Cass rame for type 10 (16 bytes	60691	ED13	Gas name for type 10 (5 bytes)			Name 10 Byte 5
ED14   Cass strattened name   Cass rame for type 1 (16 bytes)   ED14   Cass rame for type 2 (16 bytes)   Cass rame for type 2 (16 bytes)   Cass rame for type 10 (16 bytes)   Cass rame for					11 21 21 21	Σ Σ 1
ED14   Cass strictle-and name   Cass name for type 1 (16 bytes)   Cass name for type 2 (16 bytes)   Name 2 Byte 1		SDBC			1181 1181 1181	118 118 119 119 119 119 119 119 119 119
ED14   Case name for type 1 (16 bytes)   Name 2 Byte 1	26909	ED14	Gas shortened name			
Case name for type 2 (16 bytes)   Name 2 Byte 1   Septembro 1   Septembro 2   Septembro 3   Septembro 4   Septembro 6   Septem	60692	ED14	Gas name for type 1 (16 bytes)			Name 1 Byte 2
ED63   Cas name for type 10 (16 bytes)   Name 10 Byte 15     ED64   Display format   ED64   Type 1 (1 byte)   Type 2 (1 byte)   Type 2 (1 byte)   Type 3 (1 byte)   Type 3 (1 byte)   Type 4 (1 byte)   Type 4 (1 byte)   Type 9 (1 byte)   Type 10 (1 byte)   Type 10 (1 byte)   Type 9 (1 byte)   Type 9 (1 byte)   Type 10 (1 byte)   Type 10 (1 byte)   Type 9 (1 byte)   Type 10 (1 byte)   Type 10 (1 byte)   Type 9 (1 byte)   Type 9 (1 byte)   Type 10 (1 byte)   Type 10 (1 byte)   Type 9 (1 byte)   Type 10 (1 byte)   Type 10 (1 byte)   Type 9 (1 byte)   Type 9 (1 byte)   Type 10 (1 byt	66909	ED1B	Gas name for type 2 (16 bytes)			Name 2 Byte 2
ED63   Cass name for type 10 (16 bytes)   Name 10 Byte 15						
DBUS   Display format   Display format   DBUS   DB   DB   DB   DB   DB   DB   DB   D	60771	ED63	Gas name for type 10 (16 bytes)			Name 10 Byte 16
LD64         Display format         Type 2(1 byte)         Type 4(1 byte)         Type 4(1 byte)         Z bytes         Display format code type 1           ED65         Type 3(1 byte)         Type 4(1 byte)         Z bytes         Display format code type 3           ED68         Type 9(1 byte)         Type 4(1 byte)         Z bytes         Display format code type 3						
Display format   日本   日本   日本   日本   日本   日本   日本   日					11 11 11 10	1 2 2 9
ED64         Display format         Type 2(1 byte)         2 bytes           ED65         Type 3(1 byte)         Type 4(1 byte)         2 bytes           ED65         Type 3(1 byte)         2 bytes         2 bytes            Type 9(1 byte)         2 bytes         2 bytes		JBUS			118 118 118	#8 #18 #18 #18 #18 #18
ED64         Type 3 (1 byte)         Type 2 (1 byte)         2 bytes           ED65         Type 3 (1 byte)         Type 4 (1 byte)         2 bytes           ED68         Type 9 (1 byte)         Type 10 (1 byte)         2 bytes	60772	ED64	Display format			
ED65 Type 3 (1 byte)   Type 4 (1 byte)   2 bytes	60772	ED84		2 (1 byte)	Display format code type 1	Display format code type 2
ED68 Type 9 (1 byte) Type 10 (1 byte) 2 bytes	60773	ED85			Display format code type 3	Display format code type 4
	80776	ED68			Display format code fythe 9	Display format code type 10
0 = Integer : 1 = 1  dist  start the result $(0.00) : 2 = 2  dist$ start the point $(0.00)$				l		

0.18				Г	[]	0	18					
1118		feaanunsm FIA=F	Jəsəi unamı FIA=F		İəsəi unsmit N=t		18		levisnonilNA=0	teve1ori NA=0		nevenonillA≕(
2118			1saen unem SIA=f		1saen unsm SIA=f	⊢	:18		eve nor ave	neve nori SIA=0		ieve roni ⊠A=0
E#8		feaeπunsm.€M=f	1eaen unam EM=f		teset unsm.€IA=f	⊢	:18		ievs πori 81A=0	nevs nori 8lA=0		1evs non 8lA=0
		teaen unam MA=t	teser unem MA=t		teser unsm.MA=t	⊢			neveroni MA=0	nevs tori blA=0		neveroni MA=(
1718		J=overtange	1=overrange		f=overrange	⊢	18		iewsnoniNA=0	teverani NA=0		nevsnonillA≕(
9118						⊢	18		eve roni ⊈A=0	neve nori SIA=0		teve toni ⊈A=0
9 118						⊢	18		everonitA⇔0	nevs nori EIA=0		1e∧s noni 8lA=0
7 118						1	18		nevs noni MA=0	nevs nori ≱lA=0		neveroni ≱lA=(
8 11/9		teearunam MA=t	teser unem tiA=t		teser unem tiA=t	8	318		ievisnoni NA≕0	nevenori NA=0		ieveroniNA≕(
6 118		jesetunsm SIA=f	jese⊓unem SIA=t		jesenunem SIA=t	6	318		everoni∑lA=0	neve tori SIA=0		neveroni ⊈A=0
or ha		leaenunsm ElA=f	lesenunem ElA=f		besenunem ElA=f	01	18		ievs noni 81A=0	neve toni 8IA=0		teve non i 8lA=0
rr 118			jeserunam ⊅M=t		iesenunem ⊅M=t	LL	18			nevs nori MA=0		neveroniblA=(
Sr 119		ј=сиензиде	1=cve nange		e6ueu evo=↓	ZI	18			nevs nori MA=0		heveronitA=(
EI 113		,	,			13	18			neveroni SIA=0		iewsnoni⊠A=0
141 118						tri	18			neva nori 8lA=0 neva nori 8lA=0		19ve nori 8A=0 74 increase
ar 118						91	. 18			Teve ori 4tA=0		1e∧BonitAA=0
_			_	H		L			zowo ogi NA≡0			
		Dytes	2 Dytes		2 bytes				bytes	bytes		2 bytes
		2	2		2				2	2		2
												_
		byte)	byte)		byte)				byte)	byte)		Market September 1
		Type 2 (1 byte)	Type 4 (1 byte)		Type 10 (1 byte)				Type 2 (1 byte)	Type 4 (1 byte)		Done 10 (1 byte)
		Type	Type		J.pe				) yes	Jype		902
								aam				
	<b>ILLER</b>							easing alarm				
	8 pag							ecrea				
	EUI J	byte)	pyte)		byte)			000	) Afe	byte)		e page
	0 De(	Type 1 (1 byte)	Type 3 (1 byte)		Type 9 (1 byte)			Dusseuc	Type 1 (1 byte)	Type 3 (1 byte)		Tope 971 bytel
	Enal	Туре	Type	:	Туре			lncre	Type	Туре	:	706
Snac	69CE	69C3	ED6A		EDGD		JBUS	39C3	39C3	ED6F		2,013
8	Ξ	Н		-	Ш			Ξ	Ш	Ш		
	_		201		_			2	Ν.	m		
	11109	7.2209	8778		60781			28/09	28709	60783		98209
											_	

	JBUS			9L 118	21 12 21 13 21 13 21 16 21 16
60787	ED73	Reserve COMCPS			
60787	ED73	Type 1 (1 byte)	Type 2 (1 byte) 2	2 bytes	
60788	ED74	Type 3 (1 byte)	Type 4 (1 byte) 2	2 bytes	
60791	ED77	Type 9 (1 byte)	Type 10 (1 byte) 2	2 bytes	
				91	2 E E E E E E E E E E E E E E E E E E E
	JBUS			. BU	1181 - 11
60792	ED78	Aarm Delay			
60792	ED78	Aarm 1 Delay	Type 1	Word 2 bytes	es (16 bits not signed)
60793	ED79	Aarm 1 Delay	Type 2	Word 2 bytes	es (16 bits not signed)
60794	ED7A	Asm 1 Delay	Type 3	Word 2 byte	bytes (16 bits not stgned)
60801	ED81	Aarm 1 Delay	Type 10	Word 2 bytes	es (16 bits not signed)
60802	ED82	Asm 1 Delay	Type 1	Word 2 bytes	es (16 bits not signed)
60803	ED83	Asrm2 Delay		Word 2 bytes	es (16 bits not signed)
60804	ED84	Alarm2 Delay	Type 3	Word 2 bytes	es (16 bits not signed)
60811	ED8B	Alarm2 Delay	Type 10	Word 2 byte	2 bytes (16 bits not signed)
60831	ED9F	Aarm 4 Delay	Type 10	Word 2 byte	2 bytes (16 bits not signed)
				91	2
	JBUS			118	1118 1119 1119 1119 1119 1119 1119 1119
60832	EDAO	Detector type Range		_	
60832	EDAO	Range	Type 1	Word 2 byte	2 bytes (16 bits not signed)
60833	EDA1	Range	Type 2	Word 2 byte	2 bytes (16 bits not signed)
60834	EDA2	Range	Type 3	Word 2 bytes	es (16 bits not signed)
60841	EDA9	Range	Type 10	Word 2 byte	2 bytes (16 bits not signed)

## **Chapter 9 UE Declaration of Conformity**



#### DECLARATION UE DE CONFORMITE **EU Declaration of Conformity**



La société Oldham S.A.S., ZI Est 62000 Arras France, atteste que la Oldham S.A.S. company, ZI Est 62000 Arras France, declares that the

#### Système de mesure CPS –Monitoring system CPS

Incluant la centrale de mesure, les détecteurs de gaz, les modules E/S et relais Including the controller, the gas detectors, the relays and I/O modules

> est conforme aux exigences de: complies with the requirements of the following Directives:

#### Directive Européenne CEM 2014/30/UE du 26/02/14: Compatibilité Electromagnétique

The European Directive EMC 2014/30/UE dated from 26/02/14: Electromagnetic Compatibility

Normes harmonisées appliquées: EN 50270:06 for type 1&2 CEM-Appareils de détection de gaz Harmonised applied Standards

EMC-Apparatus for the detection of gases

#### II) Directive Européenne DBT 2014/35/UE du 26/02/14: Basse Tension

The European Directive LVD 2014/35/UE dated from 26/02/14: Low Voltage

Normes harmonisées appliquées: EN 61010-1:10

Harmonised applied Standard

Règles de sécurité pour appareils

électriques de mesurage

Safety requirements for electrical equipment for measurement

#### III) Norme de performance métrologique

Metrology Performance Standard

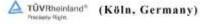
Normes appliquée Applied Standard

Organisme certificateur Certification Body

Rapport d'essai Test Report

VDI 2053:04, Annex2,

Mesure du CO (CO measurement)



S274 2007 T1

Arras, le 20/04/2016 (April 20th, 2016)

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Michel Spellemaeker

Global Director of Product Management

UE\_CPS\_revA



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